

ETSI TS 126 268 V8.0.0 (2009-04)

Technical Specification

**Digital cellular telecommunications system (Phase 2+);
Universal Mobile Telecommunications System (UMTS);
eCall data transfer;
In-band modem solution;
ANSI-C reference code
(3GPP TS 26.268 version 8.0.0 Release 8)**



Reference

RTS/TSGS-0426268v800

Keywords

GSM, UMTS

ETSI

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Sous-Préfecture de Grasse (06) N° 7803/88

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1 Scope

The present document contains an electronic copy of the ANSI-C code for the eCall in-band modem solution for reliable transmission of MSD data from IVS to PSAP via the speech channel of cellular networks. The ANSI-C code is necessary for a bit exact implementation of the IVS modem and PSAP modem described in 3GPP TS 26.267 [1].

2 References

The following documents contain provisions which, through reference in this text, constitute provisions of the present document.

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[1] 3GPP TS 26.267: "eCall Data Transfer; In-band modem solution; General description".

See also the references in 3GPP TS 26.267 [1].

3 Abbreviations

For the purpose of the present document, the following abbreviations apply:

| | |
|------|---|
| ACK | ACKnowledgement |
| ANSI | American National Standards Institute |
| CRC | Cyclic Redundancy Check |
| FEC | Forward Error Correction |
| GSM | Global System for Mobile communications |
| HARQ | Hybrid Automatic Repeat-reQuest |
| I/O | Input/Output |
| IVS | In-Vehicle System |
| MSD | Minimum Set of Data |
| NACK | Negative ACKnowledgement |
| PCM | Pulse Code Modulation |
| PSAP | Public Safety Answering Point |
| RAM | Random Access Memory |
| ROM | Read Only Memory |
| RX | Receive |
| TX | Transmit |

4 C code structure

This clause gives an overview of the structure of the bit-exact C code and provides an overview of the contents and organization of the C code attached to the present document.

The C code has been verified on the following systems:

- Windows XP SP2 and Microsoft Visual Studio V8.0;
- Linux (Suse Linux) using the gcc v3.4.2 and v4.1.2 compilers.

4.1 Contents of the C source code

The distributed files with suffix "c" contain the source code and the files with suffix "h" are the header files.

Further explanation on the files is given in the `readme.txt` file, which is reproduced in part here:

```

Package Contents
-----
folder 'ecall':
    Contains the complete eCall ANSI C fixed-point reference source code.

    modem_ivs.c      : top-level modem implementation for IVS
    modem_psap.c     : top-level modem implementation for PSAP

    modemx.h         : header file for both modem_ivs.c and modem_psap.c

    ecall_defines.h  : compile time options and preprocessor constants

    ecall_fec.h      : header file FEC encoder and decoder
    ecall_modem.h    : header file modulator and demodulator
    ecall_sync.h     : header file synchronization
    ecall_rom.h      : header file ROM data

    ecall_fec.c      : FEC encoder and decoder
    ecall_modem.c    : modulator and demodulator
    ecall_sync.c     : synchronization
    ecall_rom.c      : ROM data

folder 'pcm':
    Contains PCM data files for offline testing of the eCall IVS and PSAP
    modems, with the standalone wrapper invoking the interface functions.
    The PCM format is 16 bit signed, little endian, at 8 kHz sampling rate.
    The data files reflect 26 test cases and were generated from the eCall
    simulation framework.

    campaign_short.txt : configuration file for the 26 test cases

    pcndlout<index>.pcm : output PCM data of DL vocoder = input to IVS
    pcmlout<index>.pcm : output PCM data of UL vocoder = input to PSAP

    pcndlins<index>.pcm : test vectors for PSAP modem output
    pcmlins<index>.pcm : test vectors for IVS modem output

folder 'TEST_SETUP':
    Contains a test setup for an eCall transmission.

standalone.c
    main() wrapper to run the IVS or PSAP modem on prestored PCM data

standalone.h
    header file for standalone.c

Makefile.win
    Microsoft Visual Studio 2005/2008 Makefile
    Builds 'standalone.exe' from standalone.c and the eCall sources,
    build options are RELEASE and DEBUG.

Makefile.glx
    GNU Linux Makefile using gcc
    Builds 'standalone' from standalone.c and the eCall sources,
    build options are RELEASE and DEBUG.

verify.bat
    Windows batch file

```

Runs 'standalone.exe' in mode '-m ivs' and '-m psap' on 26 test cases (folder 'pcm') and performs a test vector comparison to the respective modem output PCM data.

```
verify.sh
Linux shell script
Runs 'standalone' in mode '-m ivs' and '-m psap' on 26 test cases
(folder 'pcm') and performs a test vector comparison to the respective
modem output PCM data.
```

4.2 Program execution

An explanation on code compilation and execution is given in the `readme.txt` file, which is reproduced in part here:

Getting Started

3GPP TS 26.268 provides the eCall modem source code and a standalone wrapper which allows to run either the IVS or PSAP modem on prestored PCM data. Five functions represent the eCall modem interface:

- * PsapSendStart
- * PsapReset
- * PsapProcess
- * IvsReset
- * IvsProcess

The external application must in addition implement the callback function `PsapReceiveMsd`, which the PSAP modem will call once the MSD was successfully received. See `standalone.c` for an example.

For a real-time simulation over 3GPP FR and AMR vocoders and to log PCM data as input to the standalone wrapper, the eCall sources have to be integrated into a simulation framework (test setup); the one used in the 3GPP selection tests is attached in the subfolder `TEST_SETUP`. The basic integration steps are briefly described below.

In order to compile and run the eCall modem code, follow the instructions given below. For code testing, two batch files have been provided:

- * `verify.bat` : MS Windows systems
- * `verify.sh` : Linux systems

They run the standalone wrapper in both IVS and PSAP mode on PCM data files that belong to the 26 test cases of `campaign_short.txt` (`TEST_SETUP`). In PSAP mode, you should see the message 'MSD received!' on completion of each test case. The output PCM files in folder 'out' are finally compared to the test vectors in folder 'pcm'.

Code Compilation

MS Windows systems

To build `standalone.exe` from `standalone.c` and the eCall sources, start with opening a new project in Visual Studio 2005/2008.

Choose File -> New -> 'Project from Existing Code' and follow the instructions of the 'Create Project from Existing Code Files Wizard'. Configuration:

- * Type of project: Visual C++
- * Specify the folder location of `standalone.c` and a project name
- * Button 'Next'
- * Select 'Use external build system'

* For Debug and Release configuration, specify
 Build command line: nmake -f Makefile.win
 Clean command line: nmake -f Makefile.win clean
 Build the project with shorthand key 'F7' or from the menu.
 The source code should compile without any errors or warnings.
 Run 'verify.bat' to verify the executable against the test vectors.

GNU Linux systems
 Compilation under Linux has been tested with

* GNU Make version 3.81
 * gcc version 4.1.3 and 4.2.4

For building the executable 'standalone' and cleanup, use

make -f Makefile.glx
 make -f Makefile.glx clean

On the platforms tested, the code compiled without errors or warnings.
 Run 'verify.sh' to verify the executable against the test vectors.

Simulation Framework

See LICENSE.TXT and README.TXT in folder TEST_SETUP for terms of usage!

Note that this simulation framework has to be compiled and run on MS Windows operating systems, as Windows specific API functions are used and the FR and AMR vocoders are attached to the framework in form of Windows executables.

To attach the eCall sources to the framework, copy the 'ecall' folder into the 'c' folder of directory TEST_SETUP. Compile and link the *.c files under subfolder 'ecall' by adding their corresponding object files to the list of makefile targets. Note that modem_ivs.c and modem_psap.c replace the code template modem_demo.c.

4.3 Variables, constants and tables

4.3.1 Description of constants used in the C-code

This clause contains a listing of all global constants defined in ecallDefines.h., together with some explanatory comments.

| Constant | Value | Description |
|------------------------|-----------------------|-------------------------------------|
| #define MAX(a,b) | ((a)>(b) ? (a) : (b)) | |
| #define MIN(a,b) | ((a)<(b) ? (a) : (b)) | |
| #define ABS(a) | ((a)<0 ? (-a) : (a)) | |
| #define SIGN(a) | ((a)<0 ? (-1) : (1)) | |
| #define PCM_LENGTH | 160 | length of PCM frame |
| #define MSD_MAX_LENGTH | 140 | length of MSD message (bytes) |
| /* Synchronization */ | | |
| #define SYNC_EVENTS | (3) | sync events required at IVS |
| #define SYNC_BADCHECKS | (8) | IVS subsequent bad checks |
| #define SYNC_IDXLEN | (75) | sync index length |
| #define SYNC_THRESHOLD | (10e6) | sync threshold |
| #define LOCK_START | (3) | number of START to lock sync |
| #define FAIL_RESTART | (3) | number of START messages to restart |

```

#define NRF_WAKEUP           (3)          number of wakeup frames
#define NRF_SYNC              (13)         length of sync in frames
#define NRF_SYNCOBSV          (10)         number of frames the PSAP checks for a
                                         better sync after detecting a preamble

#define PNSEQ_OSF             (22)         "oversampling" rate of PN sequence
#define PEAK_DIST_PP           (30*PNSEQ_OSF) distance outer positive peaks
#define PEAK_DIST_NN           (54*PNSEQ_OSF) distance negative peaks
#define PEAK_DIST_PN           (12*PNSEQ_OSF) distance positive to negative

/* Uplink/Downlink format */
#define ARQ_MAX                (8)          number of redundancy versions
#define NRB_TAIL                (3)          number of encoder tail bits
#define NRB_CRC                 (28)         order of CRC polynomial

#define NRB_INFO               (8*MSD_MAX_LENGTH)
#define NRB_INFO_CRC            (8*MSD_MAX_LENGTH + NRB_CRC)
#define NRB_CODE_ARQ             (1380)
#define NRB_CODE_BUFFER          (3*(8*MSD_MAX_LENGTH + NRB_CRC) + 4*NRB_TAIL)

#define NRF_DL DATA             (3)          DL data part
#define NRF_DL_MUTE1             (2)          DL 1st muting (after sync)
#define NRF_DL_MUTE2             (2)          DL 2nd muting (after data)
#define NRF_DL_CHUNK              (NRN_SYNC + NRF_DL_MUTE1 + NRF_DL DATA + NRF_DL_MUTE2)

/* IVS/PSAP processing */
#define NRF_MEMIVS              (5)          buffer size in frames (IVS)
#define NRF_MEMPSAP              (2)          buffer size in frames (PSAP)
#define NRS_MEMSYNC              (820)        memory size in samples (SYNC)

#define IVS_THRESHOLD            (40000)      threshold feedback messages
#define IVS_GOSTART              (6)          threshold for unreliable START
#define IVS_TXFAST                (10)         fast modulator mode NACK condition
#define IVS_TXINC                 (87)         sample increment at restart

#define FEC_VAR                  (30206)      variance: 1/4550000 in Q37
#define FEC_MEAN                  (0xB9999A)   mean: 5.8 in Q21
#define FEC_ITERATIONS             (8)          number of decoder iterations
#define FEC_STATES                  (8)          number of decoder states

#define IntLLR                   Int16         size of soft bit buffer variables
#define LLR_MAX                  ((Int32)(0x7fff-1))
#define LOGEXP_RES                  (401)        resolution of LOGEXP table
#define LOGEXP_DELTA                (-6)         determines internal Q-factor
#define LOGEXP_QIN                  (8)          input Q-factor of LLR values

```

4.3.2 Type Definitions

The following type definitions have been used, which are defined in ecallDefines.h, ecallModem.h, ecallSync.h, and modemx.h:

| Definition | Description | |
|---|-------------|---|
| typedef signed char | Int8; | 8 bit signed variable |
| typedef signed short int | Int16; | 16 bit signed variable |
| typedef signed int | Int32; | 32 bit signed variable |
| typedef unsigned char | Ord1; | binary symbol |
| typedef unsigned char | Ord8; | 8 bit unsigned variable |
| typedef unsigned short int | Ord16; | 16 bit unsigned variable |
| typedef unsigned int | Ord32; | 32 bit unsigned variable |
| typedef enum { Mod3bit4smp, Mod3bit8smp } ModType; | | modulator type for uplink transmission |
| typedef struct { Int16 bpsym; Int16 spmf; | | bits per symbol samples per modulation frame |

```

Int16 mfpf;
Int16 decpos1;
Int16 decpos2;
Int16 wutperiod;
Int16 nfmute1;
Int16 nfmute4;
Int16 nfmuteall;
Int16 nfdata;

modulation frames per frame = PCM_LENGTH/spmf
position 1st decoding trial
position 2nd decoding trial
wakeup tone period in samples
number of muting frames 1st interval
number of muting frames 4th interval
number of muting frames total
number of data frames = NRB_CODE_ARQ/ (mfpf*bpsym)

const Int16 *ulPulse;
const Int16 *ulPulseMatch;
const Int16 *mgTable;
const Int16 *wakeupSin;
const Int16 *wakeupCos;
} ModState;                                modulator state for uplink transmission

typedef struct {
    Int32 *state;
    Int32 *wakeupState;                      memory for wakeup tone detector

    Int32 amplitude[3];
    Int16 corrIndex[4];
    Int32 checkMem[4];
    Int16 peakPos[4];

    Int16 checkCounter;
    Int16 obsvCounter;
    Int16 msgCounter;

    Int16 index;
    Int16 offset;
    Int16 delay;
    Int16 tempDelay;
    Int16 prevDelay;
    Int16 trials;
    Int16 npeaks;
    Int16 events;

    Ord1 flag;
    Ord1 checkOk;
} SyncState;                                indicates successful sync
                                                indicates successful sync check
                                                state of synchronization functions

typedef enum {
    DlMsgStart,
    DlMsgNack,
    DlMsgAck,
    DlMsgIdle
} DlData;                                    downlink message identifiers

typedef enum {
    IvsIdle,
    IvsSendMsd
} IvsState;                                 IVS state identifiers

typedef struct {
    ModState mod;                           IVS modulator struct */
    SyncState sync;                         IVS sync struct */

    Int32 syncBuffer[NRS_MEMSYNC];
    Int16 delayBuffer[2*PCM_LENGTH];
    Int16 pcmBuffer[NRF_MEMIVS*PCM_LENGTH];
    Ord1 bitBuffer[NRB_CODE_BUFFER];

    Int16 state;                            IVS state
    Int16 stateCnt[4];                     state counters
    Int16 startCntIgnore;                  counts unreliable START messages
    Int16 globalNackCnt;                  counts NACK messages

    Int16 txN;                             TX number of frames
    Int16 txIndex;                        TX frame counter
    Int16 txRedVer;                       TX redundancy version

```

```

Int16 txDelay;
Int16 rxN;
Int16 rxIndex;
Int16 rxRead;
} IvsData;

typedef enum {
    PsapIdle,
    PsapStart,
    PsapNack,
    PsapAck,
    PsapTrigger,
    PsapStartToTrigger
} PsapState;                                PSAP state identifiers

typedef struct {
    ModState mod;                            PSAP modulator struct
    SyncState sync;                          PSAP sync struct

    Ord8 *msd;                             MSD in byte representation
    Ord1 *msdBin;                          MSD in binary representation
    Int16 *pcmBuffer;                      sync buffer
    IntLLR *bitBuffer;                     soft bit buffer for decoding

    char buffer[0
        + sizeof(IntLLR) * NRB_CODE_ARQ
        + sizeof(Int16) * NRF_MEMPSAP*PCM_LENGTH
        + sizeof(Int32) * NRS_MEMSYNC
        + sizeof(Int32) * 2*(NRF_SYNC+1)];
}

Int16 state;                                PSAP state
Int16 dlData;                               downlink message symbol

Int16 txN;                                  TX number of frames
Int16 txIndex;                             TX frame counter
Int16 mgIndex;                            RX current position in muting gap table
Int16 rxN;                                 RX number of frames (without muting)
Int16 rxIndex;                            RX frame counter
Int16 rxRedVer;                           RX redundancy version
Int16 rxDecTrials;                        RX decoding trails
} PsapData;                                struct that gathers parameters relevant at PSAP

```

4.3.3 Description of fixed tables used in the C-code

This clause contains a listing of all fixed tables (ROM) defined in `ecall_rom.c`.

| Type/Constant | Dimension | Description |
|-------------------------------------|---------------|-----------------------------------|
| <i>/* Synchronization */</i> | | |
| Int16 wakeupSin500 | [16] | sine waveform at 500 Hz |
| Int16 wakeupCos500 | [16] | cosine waveform at 500 Hz |
| Int16 wakeupSin800 | [10] | sine waveform at 800 Hz |
| Int16 wakeupCos800 | [10] | cosine waveform at 800 Hz |
| Int16 syncPulseForm | [5] | sync pulse |
| Int16 syncSequence | [15] | sync pulse sequence |
| Int16 syncIndexPreamble | [SYNC_IDXLEN] | sync pulse positions |
| Int16 syncFrame | [1600] | predefined synchronization signal |
| <i>/* Uplink/Downlink format */</i> | | |
| Int16 indexBits | [24] | bit positions for turbo decoder |
| <i>// fast modulator mode:</i> | | |
| Int16 m4smp_ulPulse | [16] | uplink waveform |
| Int16 m4smp_ulPulseMatch | [64] | matched filtered uplink waveform |
| Int16 m4smp_mgTable | [54] | table indicating muting gaps |
| <i>// robust modulator mode:</i> | | |
| Int16 m8smp_ulPulse | [32] | uplink waveform |
| Int16 m8smp_ulPulseMatch | [128] | matched filtered uplink waveform |

| | | |
|---------------------------|------------------------------|--------------------------------|
| Int16 m8smp_mgTable | [104] | table indicating muting gaps |
| Int16 dlPcmData | [4] [NRF_DL DATA*PCM_LENGTH] | downlink transmit signal |
| Int16 dlPcmDataMatch | [4] [NRF_DL DATA*PCM_LENGTH] | DL MF signal |
| /* FEC encoder/decoder */ | | |
| Ord16 stateTransMat | [8] [2] | FEC: state transitions |
| Ord16 stateTrans | [16] | FEC: state transitions |
| Ord16 revStateTransMat | [8] [2] | FEC: reverse state transitions |
| Ord16 revStateTrans | [16] | FEC: reverse state transitions |
| Ord1 outputParityMat | [8] [2] | FEC: output parity indicator |
| Ord1 outputParity | [16] | FEC: output parity indicator |
| Ord1 crcPolynomial | [NRB_CRC+1] | coefficients of CRC polynomial |
| Ord1 scramblingSeq | [NRB_INFO_CRC] | bit scrambling sequence |
| Ord16 interleaverSeq | [NRB_INFO_CRC] | interleaver sequence |
| Ord16 redVerIndex | [8] [NRB_CODE_ARQ] | index vector for HARQ process |
| IntLLR logExpTable | [LOGEXP_RES] | lookup table (logExp function) |

4.3.4 Static variables used in the C-code

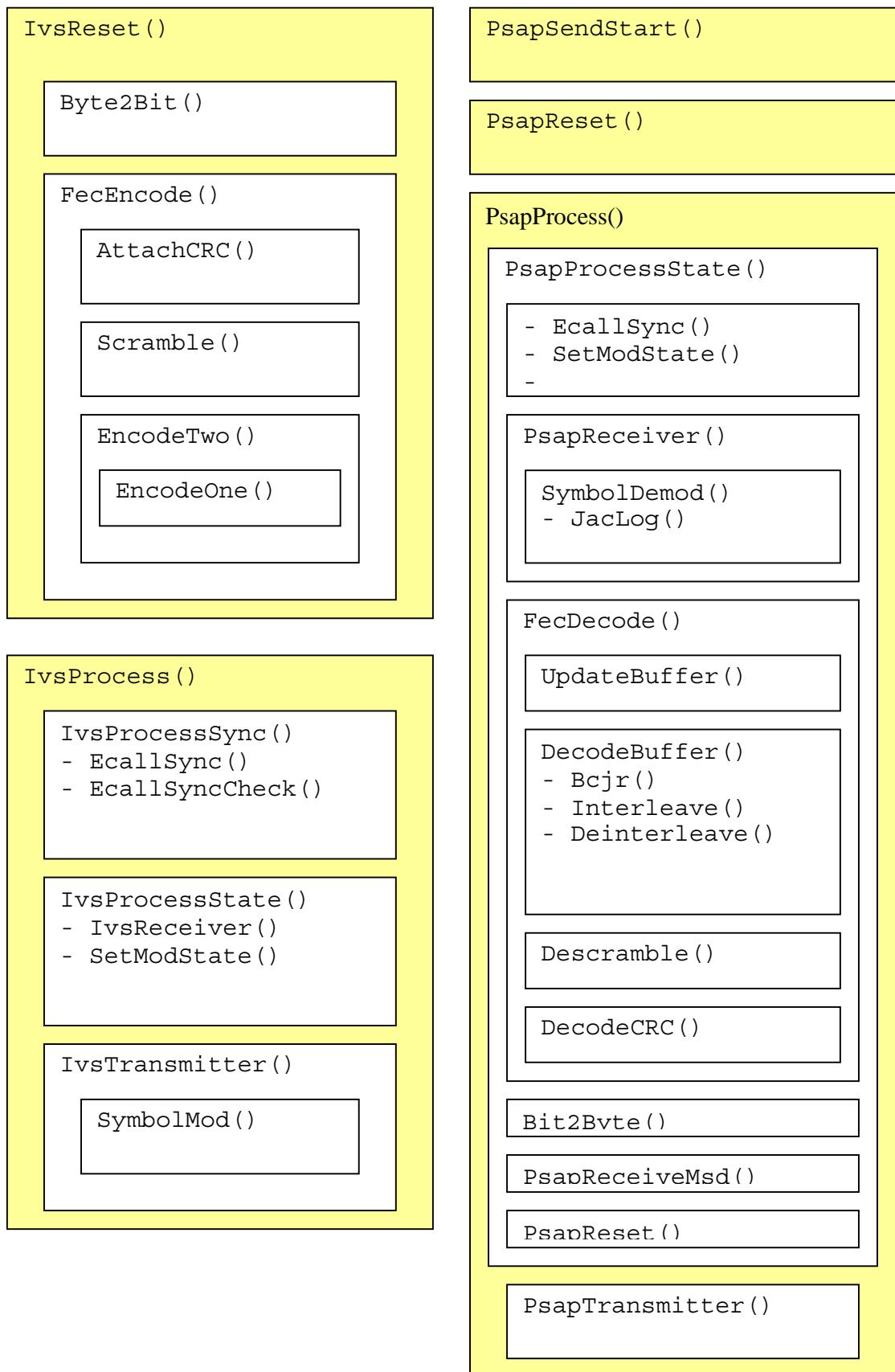
This clause contains a listing of static variables (RAM) defined in source files.

| Definition | Description |
|--|----------------------------------|
| IvsData ivs | IVS static memory |
| PsapData psap | PSAP static memory |
| WordLLR chCodedSoftBitBuffer [NRB_CODE_BUFFER] | soft bit buffer of turbo decoder |

4.4 Functions of the C Code

This clause contains the headers of the employed IVS and PSAP functions. They correspond to a large extent to the functional description of the IVS and PSAP provided in 3GPP TS 26.267 [1].

Figure 1 gives an overview of the most important functions and their hierarchical relation.

**Figure 1: Hierarchical function overview**

4.4.1 Interface functions

```
/*=====
/* IVS implementation: IvsReset
/*
/* Description: Reset of IVS before the reception of a new MSD
/*
/* In: const Ord8* msd      -> MSD to be transmitted
/*      int          length   -> MSD length (equal to MSD_MAX_LENGTH)
/*
void IvsReset(const Ord8 *msd, int length)

/*=====
/* IVS implementation: IvsProcess
/*
/* Description: IVS modem function that processes the PCM data
/*
/* InOut: Int16* pcm <-> input and output frame of 16bit PCM samples
/*
void IvsProcess(Int16 *pcm)

/*=====
/* PSAP implementation: PsapSendStart
/*
/* Description: Initiates PSAP to trigger the transmission of an MSD
/*
void PsapSendStart()

/*=====
/* PSAP implementation: PsapReset
/*
/* Description: Reset of PSAP before the reception of a new MSD
/*
void PsapReset()

/*=====
/* PSAP implementation: PsapProcess
/*
/* Description: PSAP modem function that processes the PCM data
/*
/* InOut: Int16* pcm <-> input and output frame of 16bit PCM samples
/*
void PsapProcess(Int16 *pcm)
```

4.4.2 IVS transmitter functions

```
/*=====
/* IVS FUNCTION: IvsTransmitter
/*
/* Description: IVS transmitter function
/*
/* In:    const ModState* ms      -> modulator struct
/*        const Ord1*     buffer  -> code bit buffer
/*        Int16          rv       -> redundancy version
/*        Int16          index    -> position within uplink frame
/* Out:   Int16*      pcm      <- output data
/*
void IvsTransmitter(const ModState *ms, const Ord1 *buffer, Int16 *pcm,
                    Int16 rv, Int16 index)
```

```

/*=====
/* IVS FUNCTION: SymbolMod
/*
/* Description: symbol modulator
/*
/* In:     const ModState* ms      -> modulator struct
/*          Int16        symbol   -> symbol index
/* Out:    Int16*      mPulse   <- modulated output sequence
/*
void SymbolMod(const ModState *ms, Int16 symbol, Int16 *mPulse)

/*=====
/* IVS FUNCTION: Byte2Bit
/*
/* Description: conversion byte vector to bit vector
/*
/* In:     Ord8* in       -> vector of input bytes
/*          Int16 length  -> length of input
/* Out:    Ord1* out      <- vector of output bits
/*
void Byte2Bit(const Ord8 *in, Ord1 *out, Int16 length)

/*=====
/* ENCODER FUNCTION: FecEncode
/*
/* Description: encoding of MSD
/*
/* InOut: Ord1 *buffer  <-> takes info bits and returns coded bits
/*
void FecEncode(Ord1 *buffer)

/*=====
/* ENCODER FUNCTION: AttachCrc
/*
/* Description: attaches CRC bits
/*
/* In:     const Ord1* infoBits  -> input information bits
/* Out:    Ord1*      infoWithCrc <- bits with CRC attached
/*
void AttachCrc(const Ord1 *infoBits, Ord1 *infoWithCrc)

/*=====
/* ENCODER FUNCTION: Scramble
/*
/* Description: bit scrambling
/*
/* In:     const Ord1* in      -> non scrambled input bit sequence
/* Out:    Ord1*      out     <- scrambled output bit sequence
/*
void Scramble(const Ord1 *in, Ord1 *out)

/*=====
/* ENCODER FUNCTION: EncodeTwo
/*
/* Description: encoding of bit sequence
/*
/* InOut: Ord1* codedBits  <-> scrambled bits to coded bits
/*
void EncodeTwo(Ord1 *codedBits)

```

```
/*=====
/* ENCODER FUNCTION: EncodeOne
/*
/* Description: convolutional encoding of each component
/*
/* In:     Int16 encNr      -> component number
/* InOut:  Ord1* codedBits  <-> bits to be encoded
/*
void EncodeOne(Ord1 *codedBits, Int16 encNr)
```

4.4.3 PSAP receiver functions

```
/*=====
/* UTILITY FUNCTION: PsapProcessState
/*
/* Description: PSAP state machine, determines PSAP receiver operation
/*           according to the state
/*
/* In:  const Int16* pcm  -> input frame of 16bit PCM samples
/*
void PsapProcessState(const Int16 *pcm)
```

```
/*=====
/* PSAP FUNCTION: PsapReceiver
/*
/* Description: PSAP receiver function (decoding is done outside)
/*
/* In:    const ModState* ms      -> modulator struct
/*        const Int16*   pcm      -> input data for demodulation
/* Out:   IntLLR*             softBits  <- demodulated soft bit sequence
/*
void PsapReceiver(const ModState *ms, const Int16 *pcm, IntLLR *softBits)
```

```
/*=====
/* PSAP FUNCTION: SymbolDemod
/*
/* Description: symbol demodulator
/*
/* In:    const ModState* ms      -> modulator struct
/*        const Int16*   mPulse   -> received pulse train
/* Out:   IntLLR*             softBits  <- demodulated soft bit sequence
/*
void SymbolDemod(const ModState *ms, const Int16 *mPulse, IntLLR *softBits)
```

```
/*=====
/* PSAP FUNCTION: Bit2Byte
/*
/* Description: conversion bit vector to byte vector
/*
/* In:    const Ord1* in       -> vector of input bits
/*        Int16      length   -> length of output
/* Out:   Ord8*      out      <- vector of output bytes
/*
void Bit2Byte(const Ord1 *in, Ord8 *out, Int16 length)
```

```
/*=====
/* PSAP FUNCTION: MpyLacc
/*
/* Description: multiply 32bit number with 16bit number (32bit result)
/*
/* In:     Int32 var32  -> 32bit number
/*        Int16 var16  -> 16bit number
/* Return: Int32      <- result
/*
Int32 MpyLacc(Int32 var32, Int16 var16)
```

```

/*=====
/* DECODER FUNCTION: FecDecode
/*
/* Description: decoding to find the MSD
/*
/* In:     const IntLLR* in    -> received soft bits
/*          Int16        rv    -> redundancy version
/* Out:    Ord1*         out   <- decoded MSD in binary representation
/* Return: Ord1           <- result of CRC check
/*
/*=====
Ord1 FecDecode(const IntLLR *in, Int16 rv, Ord1 *out)

/*=====
/* DECODER FUNCTION: UpdateBuffer
/*
/* Description: update channel LLR buffer with new soft bits
/*
/* In:     const IntLLR* softInBits    -> received soft bits
/*          Int16        rv        -> redundancy version
/* InOut:  IntLLR*      chLLRbuffer <-> decoder buffer
/*
/*=====
void UpdateBuffer(IntLLR *chLLRbuffer, const IntLLR *softInBits, Int16 rv)

/*=====
/* DECODER FUNCTION: DecodeBuffer
/*
/* Description: decoding of LLR buffer
/*
/* In:     const IntLLR* syst1       -> RX systematic soft bits
/*          const IntLLR* syst2       -> interleaved RX systematic tail bits
/*          const IntLLR* parity1     -> RX parity soft bits
/*          const IntLLR* parity2     -> interleaved RX parity soft bits
/* Out:    Ord1*        decBits    <- decoded bits
/*
/*=====
void DecodeBuffer(const IntLLR *syst1, const IntLLR *syst2,
                  const IntLLR *parity1, const IntLLR *parity2, Ord1 *decBits)

/*=====
/* DECODER FUNCTION: Bcjr
/*
/* Description: BCJR algorithm
/*
/* In:     const IntLLR* parity       -> received parity soft bits
/* InOut:  IntLLR*      extrinsic  <-> extrinsic information
/*
/*=====
void Bcjr(const IntLLR *parity, IntLLR *extrinsic)

/*=====
/* DECODER FUNCTION: Interleave
/*
/* Description: Turbo code interleaver
/*
/* In:     const IntLLR* in    -> input sequence
/* Out:    IntLLR*      out   <- output sequence
/*
/*=====
void Interleave(const IntLLR *in, IntLLR *out)

/*=====
/* DECODER FUNCTION: Deinterleave
/*
/* Description: Turbo code deinterleaver
/*
/* InOut:  IntLLR* inout  <-> input and deinterleaved output sequence
/*
/*=====
void Deinterleave(IntLLR *inout)

```

```

/*=====
/* DECODER FUNCTION: Descramble
/*
/* Description: descrambles decoded bits
/*
/* InOut: Ord1* inout <-> input and output bit sequence
/*
void Descramble(Ord1 *inout)

/*=====
/* DECODER FUNCTION: DecodeCrc
/*
/* Description: check CRC of decoded bits
/*
/* In: const Ord1* codedBits -> decoded bit sequence to be checked
/* Return: Ord1 <- result of CRC check
/*
Ord1 DecodeCrc(const Ord1 *codedBits)

/*=====
/* DECODER FUNCTION: GammaQ
/*
/* Description: compute gamma values for BCJR algorithm
/*
/* In: Int16 k -> bit position
/* Int16 l -> state
/* const IntLLR* parity -> received parity bits
/* const IntLLR* extrinsic -> sum of extrinsic and systematic bits
/* Return: IntLLR <- value of gamma(k,l)
/*
IntLLR GammaQ(Int16 k, Int16 l, const IntLLR *parity, const IntLLR *extrinsic)

/*=====
/* UTILITY FUNCTION: JacLog
/*
/* Description: Jacobian logarithm
/*
/* In: IntLLR a -> value one
/* IntLLR b -> value two
/* Return: IntLLR <- Jacobian logarithm
/*
IntLLR JacLog(Int32 a, Int32 b)

```

4.4.4 PSAP transmitter functions

```

/*=====
/* PSAP FUNCTION: PsapTransmitter
/*
/* Description: PSAP downlink transmitter (uses prestored sequences)
/*
/* In: Int16 symbol -> one out of four downlink symbols
/* Int16 index -> position within downlink frame
/* Out: Int16* pcm <- output data
/*
void PsapTransmitter(Int16 *pcm, Int16 symbol, Int16 index)

```

4.4.5 IVS receiver functions

```
/*=====
/* UTILITY FUNCTION: IvsProcessState
/*
/* Description: IVS state machine, evaluating feedback messages
/*
/* In: const Int16* buffer -> pointer to PCM DL data buffer
/*
void IvsProcessState(const Int16 *buffer)

/*=====
/* IVS FUNCTION: IvsReceiver
/*
/* Description: IVS receiver function
/*
/* In: const Int16* pcm -> input to downlink receiver
/* Out: Int32* metric <- metric[k]: k = 0..3 correlation values
/* <- metric[4]: reliability factor (-1: skip)
/* Return: Int16 <- demodulated message
/*
Int16 IvsReceiver(const Int16 *pcm, Int32 *metric)
```

4.4.6 Synchronization functions (IVS and PSAP)

```
/*=====
/* FUNCTION: EcallSync
/*
/* Description: main synchronization function
/*
/* In: const Int16* pcm -> input frame
/* const char* caller -> text to identify PSAP or IVS
/* InOut: SyncState* sync <-> sync struct
/*
void EcallSync(SyncState *sync, const Int16 *pcm, const char *caller)
```

```
/*=====
/* UTILITY FUNCTION: IvsProcessSync
/*
/* Description: IVS sync evaluation
/*
/* In: const Int16* pcm -> input frame of 16bit PCM samples
/*
void IvsProcessSync(const Int16 *pcm)
```

```
/*=====
/* IVS FUNCTION: EcallSyncCheck
/*
/* Description: checks whether sync is still valid at IVS
/*
/* In: const Int16* pcm -> input frame
/* InOut: SyncState* sync <-> sync struct
/*
void EcallSyncCheck(SyncState *sync, const Int16 *pcm)
```

```
/*=====
/* UTILITY FUNCTION: ToneDetect
/*
/* Description: tone detection at 500 Hz or 800 Hz
/*
/* In: const Int16* pcm -> input frame
/* InOut: SyncState* sync <-> sync struct
/*
void ToneDetect(SyncState *sync, const Int16 *pcm)
```

```

/*=====
/* UTILITY FUNCTION: UpdatePeak
/*
/* Description: update sync peak position
/*
/* In:      const Int32* pos    -> vector of positions
/*          const Int32* corr   -> vector of correlation values
/*          Int16        dist   -> distance to be checked
/* Return:  Int16            <- updated peak position
/*
=====
Int16 UpdatePeak(const Int32 *pos, const Int32 *corr, Int16 dist)

/*=====
/* UTILITY FUNCTION: CheckPosPeaks
/*
/* Description: check positive sync peaks
/*
/* In:      const char* caller      -> text to identify PSAP or IVS
/*          const Int32* pCorr       -> vector of correlation values
/*          Int16        p1          -> peak position p1
/*          Int16        p2          -> peak position p2
/*          Int16        ppPeaks     -> number correct pos/pos distances
/*          Int16        npPeaks     -> number correct neg/pos distances
/*          Int16        targetDelay -> target delay if sync successful
/* InOut:   SyncState* sync       <-> sync struct
/*
=====
void CheckPosPeaks(SyncState *sync, const char *caller, const Int32 *pCorr,
                    Int16 p1, Int16 p2, Int16 ppPeaks, Int16 npPeaks,
                    Int16 targetDelay)

/*=====
/* UTILITY FUNCTION: CheckNegPeaks
/*
/* Description: check negative sync peaks
/*
/* In:      const char* caller      -> text to identify PSAP or IVS
/*          const Int32* nCorr       -> vector of correlation values
/*          Int16        n1          -> peak position n1
/*          Int16        n2          -> peak position n2
/*          Int16        nnPeaks     -> number correct neg/neg distances
/*          Int16        npPeaks     -> number correct neg/pos distances
/*          Int16        targetDelay -> target delay if sync successful
/* InOut:   SyncState* sync       <-> sync struct
/*
=====
void CheckNegPeaks(SyncState *sync, const char *caller, const Int32 *nCorr,
                    Int16 n1, Int16 n2, Int16 nnPeaks, Int16 npPeaks,
                    Int16 targetDelay)

```

4.4.7 Other utility functions (IVS and PSAP)

```

/*=====
/* UTILITY FUNCTION: SetModState
/*
/* Description: set the modulator state
/*
/* In:      Int16    modType   -> type of modulator to use
/* InOut:   ModState* ms       <-> modulator struct
/*
=====
void SetModState(ModState *ms, ModType modType)

```

Annex A (informative): Change history

| Change history | | | | | | | |
|----------------|---------|-----------|----|-----|-----------------------|-------|-------|
| Date | TSG SA# | TSG Doc. | CR | Rev | Subject/Comment | Old | New |
| 2009-03 | 43 | SP-090201 | | | Approved at TSG SA#43 | 2.0.0 | 8.0.0 |
| | | | | | | | |
| | | | | | | | |

History

| Document history | | |
|------------------|------------|-------------|
| V8.0.0 | April 2009 | Publication |
| | | |
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