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Positioning Methods
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Contents

Forev	vord		4
1	Scope		5
2	References		5
3	Definitions abbreviation	ns and symbols	5
3.1		is the symbols	
3.2			
4		tents	
4.1		roadcast Message	
4.1.1 4.1.1.		a Broadcast Message Content	
4.1.1. 4.1.1.		inition IE	
4.1.1. 4.1.1.		er IE	
4.1.1. 4.1.1.		ei IE	
4.1.1.		inition IE	
4.1.1.		inition IE	
4.1.1.		S ID Definition IE	
4.1.1.		ync Definition IE	
4.1.1.		ies IE	
4.1.1.			
4.1.1.		alues IE	
4.1.1.		es IE	
4.1.1.		on IE	
4.1.1.		Location IE	
4.2		dcast Message	
4.2.1		Content	
4.2.1.	1 DGPS Correction Data		20
4.2.1.	1.1 GSM Time Present	IE	21
4.2.1.	1.2 BTS Clock Drift Pr	esent IE	21
4.2.1.	1.3 BTS Clock Drift IE		21
4.2.1.	1.4 Reference Location	IE	21
4.2.1.			
4.2.1.			
4.2.1.			
4.2.1.		Œ	
4.2.1.		Correction Data	
4.2.1.	3 Almanac and Other Da	ta	25
Anne	ex A (informative):	Overview of Broadcast Assistance for E-OTD and GPS	27
A.1	General		27
A.2		ast	
A.3			
A.4	Impact on Other Services		28
Anne	ex B (informative):	Example of E-OTD Assistance Data Broadcast Message	30
Anne	ex C (informative):	Example of GPS Assistance Data Broadcast Message	34
Anne	y D (informativa).	Changa history	25

Foreword

This Technical Specification has been produced by the 3rd Generation Partnership Project (3GPP).

The present document defines the contents of LCS assistance data broadcast messages from the Serving Mobile Location Centre (SMLC) and the Mobile Station (MS).

The contents of the present document are subject to continuing work within the TSG and may change following formal TSG approval. Should the TSG modify the contents of the present document, it will be re-released by the TSG with an identifying change of release date and an increase in version number as follows:

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- y the second digit is incremented for all changes of substance, i.e. technical enhancements, corrections, updates, etc.
- z the third digit is incremented when editorial only changes have been incorporated in the document.

1 Scope

The present document contains the content of messages necessary for support of MS Based location service operation on the mobile radio interface layer 3.

2 References

The following documents contain provisions which, through reference in this text, constitute provisions of the present document.

- References are either specific (identified by date of publication, edition number, version number, etc.) or non-specific.
- For a specific reference, subsequent revisions do not apply.
- For a non-specific reference, the latest version applies. In the case of a reference to a 3GPP document (including a GSM document), a non-specific reference implicitly refers to the latest version of that document *in the same Release as the present document*.

[1]	3GPP TS 21.905: "Vocabulary for 3GPP Specifications".
[2]	Void.
[3]	Void.
[4]	Void.
[5]	Void"
[6]	3GPP TS 23.041: "Technical Realization of Short Message Service Cell Broadcast (SMSCB)"
[7]	Void.
[8]	Void.
[9]	Void.
[10]	Void.
[11]	Void.
[12]	Void.
[13]	Void.
[14]	Void.
[15]	RTCM-SC104, RTCM Recommended Standards for Differential GNSS Service (v.2.2).
[16]	ICD-GPS-200, Navstar GPS Space Segment / Navigation User Interfaces.

3 Definitions, abbreviations and symbols

3.1 Definitions

For the purposes of the present document, the following terms and definitions apply.

E-OTD Assistance Data Message: E-OTD Assistance Data contains the RTD and BTS coordinates of the neighbours that should be used in E-OTD measurements. This E-OTD Assistance Data is broadcasted using CBCH channel using SMSCB DRX service. The reception of this broadcast message enables MS to calculate its own location.

GPS Assistance Data Message: GPS Assistance Data Message contains GPS differential corrections. The reception of this broadcast message enables MS to have calculate more accurate location estimate.

3.2 Abbreviations

Abbreviations used in the present document are listed in 3GPP TS 21.905 [1].

4 Broadcast Message Contents

This clause describes the LCS Assistance Data messages to be broadcasted in SMSCB message's content part over CBCH channel using SMSCB DRX service. The rules and contets are described so that SMLC is able to construct the message as well as MS is able to process the received message. The E-OTD Assistance Data message contains RTD and BTS coordinate information and GPS Assistance Data contains GPS Differential Correction data, Emphemeris and Clock Correction Data and Almanac and Other Data.

4.1 E-OTD Assistance Data Broadcast Message

The E-OTD Assistance Data message contents are defined in this clause. The E-OTD Assistance Data message is built so that it has always a fixed length and some of the information elements are scalable according to the amount of neighbours and the amount of sectored channels. The information elements are in the order which is described in section 4.1.1 and no spare bits are allowed between elements. The MSB bits of the information elements are presented always first and if boundary of the octet divides the information element then the LSB part of the information element continues in the LSB part of the next octet (figure 1). Example of E-OTD Assistance Data Broadcast Message is in Annex B. The channel to broadcast the E-OTD Assistance Data message is CBCH over which the SMSCB DRX service is used. One SMSCB message has fixed information data length of 82 octets and the purpose is always to use the whole fixed length message capacity for the message. MS can identify the LCS SMSCB message with E-OTD Message Identifier declared in 3GPP TS 23.041.

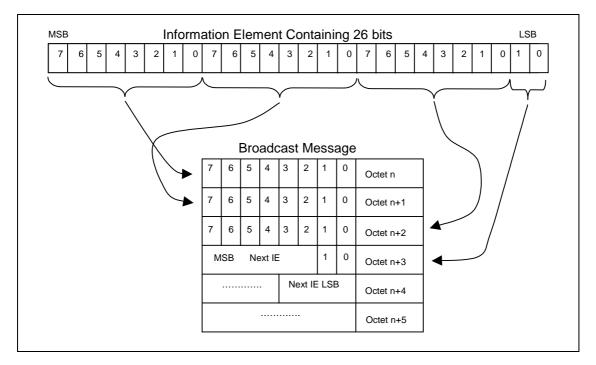


Figure 1: Information element bit mapping to the broadcast message

4.1.1 E-OTD Assistance Data Broadcast Message Content

The Broadcast Assistance Data is a point-to-multipoint message from the GSM Network to the MSs. This message gives assistance data to the MS for performing E-OTD measurements and calculating its own position. It contains the following information elements. The information elements are always in the order described in table 1. The ciphered part of message is end of message and indicated with grey shading in table 1.

Table 1: E-OTD Assistance Data Broadcast Message Content

Information element	Type/Reference	Presence
Message Structure Definition	Message Structure Definition 4.1.1.1	M
Reference Time	Reference Time 4.1.1.2	M
Ciphering Serial Number	Ciphering Serial Number 4.1.1.3	С
Time Slot Scheme	Time Slot Scheme 4.1.1.4	M
Neighbour Bitmap Definition	Neighbour BitmapDefinition 4.1.1.5	С
Sectored Channels Definition	Sectored Channels Definition 4.1.1.6	С
Sectored Channels BTS ID Definition	Sectored Channel's BTS ID Definition 4.1.1.7	С
Sectored BTS Sync/Async Definition	Sectored BTS Sync/Async Definition 4.1.1.8	С
51 Multiframe Offset Values	51 Multiframe Offset Values 4.1.1.9	M
BCC Definition	BCC Definition 4.1.1.10	M
RTD Drift Factor Values	RTD Drift Factor Values 4.1.1.11	С
Channel RTD Values	Channel RTD Values 4.1.1.12	С
Serving Cell Location	Serving Cell Location 4.1.1.13	M
Relative Neighbour Location Values	Relative Neighbour Location Values 4.1.1.14	М

4.1.1.1 Message Structure Definition IE

This IE contains the definition of this broadcast message. The length of this IE is 19 bits and it is mandatory. This IE contains the following bits:

Table 2: Message Structure Definition

Bit	Bit order in field	Definition
1	LSB	
2		Neighbour List Map (bits 2-0)
3	MSB	
4	LSB	
5		Accuracy Range (bits 2-0)
6	MSB	Accuracy Namye (bits 2-0)
7		Ciphering Key Flag
8		Cipher On/Off
9		Sector Ind
10		RTD Range
11	LSB	
12	MSB	RTD Accuracy (bits 1-0)
13		RTD Drift Factors Present
14		RTDs Present
15	LSB	
16		
17		
18		Number of Neighbours (bits 4-0)
19	MSB	

The first three octets upto bit 3 in octet 3 in the broadcast message's content part containing the Message Structure Definition IE look always as follows:

	8	7	6	5	4	3	2	1	
	Cipher On/Off	Cipher- ing Key Flag	Ac	curacy Ran (bits 2-0)	ge	Neig	ghbour List (bits 2-0)	Мар	Octet1
	Numb Neigh (bits	bours	RTDs Present	RTD Drift Factors Present	RTD Ao (bits	ccuracy 1-0)	RTD Range	Sector Ind	Octet2
Ĺ			(Next IE)			Number o	f Neighbour	s (bits 2-0)	Octet3

The definitions of each structure item is declared below:

Neighbour List Map

These bits define in which order the neighbours in the System Information Neighbour List (max 32 neighbours) are reported with the broadcast message.

The Neighbour List Map will also affect the amount of bits that can be used for Relative Neighbour Location Value definitions.

This Broadcast Assistance Data message is always referring to the neighbour BTSs included in the System Information Neighbour List which is received in idle state from BCCH. The E-OTD broadcast message does not allow the possibility for delivering assistance data for other BTSs (outside the the System Information Neighbour

0 **Definition** 2 1 0 0 0 All Neigbours from neighbour list 0 0 1 Even Neighbours from neighbour list 0 1 0 Odd Neighbours from neighbour list 1st & 1st + n*3 0 1 1 2nd & 2nd+n*3 0 0 1 3rd & 3rd+n*3 1 0 1 0 Neighbour Bitmap Definition 1 1 1 1 Spare

Table 3: Neighbour List Map

- All Neighbours means all the neighbours from System Information Neighbour list (max 32 neighbours) are reported in this broadcast message (1 broadcast message)
- Even/Odd neighbours from neighbour list means the even/odd list entries in the System Information Neighbour List are reported in this broadcast message (two broadcast messages needed)
- 1st & 1st+n*3 means that 1st, 4th, 7th, 10th,...,31st (max 11 neighbours) will be reported in this broadcast message (1/3 of total broadcast)
- 2nd & 2nd+n*3 means that 2nd, 5th, 8th, 11th, ..., 32nd (max 11 neighbours) will be reported in this broadcast message (2/3 of total broadcast)
- 3rd & 3rd+n*3 means that 3rd, 6th, 9th, 12th, ..., 30th (max 10 neighbours) will be reported in this broadcast message (3/3 of total broadcast)

The 1st & 1st+n*3, 2nd & 2nd+n*3 and 3rd & 3rd+n*3 means total 3 broadcast messages

 Neighbour Bitmap Definition will define which neighbours are included into this broadcast message, see section 4.1.1.5.

Accuracy Range

The accuracy range declares the accuracy of the values in the Relative Neigbour Location Value IE. The accuracy range has the following information:

Definition 2 0 1 0 0 0 5 km 1 0 0 10 km 0 0 15 km 1 0 1 1 20 km 1 0 0 30 km 0 1 45 km 1 1 1 0 60 km 1 1 1 120 km

Table 4: Accuracy Range

For example if there are 15 bits (1 sign bit and 14 value bits) reserved for Relative Neighbour North or East Value and the accuracy range is defined to be 20 km, then resolution of Relative Neighbour North or East Value is 0.6 m.

Ciphering Key Flag

The MS gets two (2) deciphering keys always with location update, a deciphering key that is time stamped to be current one and deciphering key that time stamped to be next one. Thus the MS has always two deciphering keys in memory. With this Ciphering Key Flag in this broadcast message the MS knows whether to use current/next deciphering key for deciphering the received broadcast message. The MS shall interpret this IE as follows:

- **Ciphering Key Flag**(previous message) = **Ciphering Key Flag**(this message) => Deciphering Key not changed
- Ciphering Key Flag(previous message) <> Cipher Key Flag(this message) => Deciphering Key changed

Cipher On/Off

This bit indicates whether this broadcast message has been ciphered or not. The RTD Drift Factor Values IE, Channel RTD Values IE, Serving Cell Location IE and Relative Neighbour Location Values IE will be ciphered if ciphering is active.

- '0' Ciphering Off
- '1' Ciphering On

Sector Ind

This bit indicates whether this broadcast message contains BTS Sectored Cell information or not.

- '0' No Sector Information included
- '1' Sector Information included

RTD Range

This bit indicates whether the RTD value covers only one time slot period or 8 time slot period. This bit will affect the RTD field so that there will be need for 3 bits more for RTD if whole 8 time slot period need to be indicated with RTD value.

- '0' RTD value covers 1 time slot period
- '1' RTD value covers 8 time slots period

RTD Accuracy

This contains two bits, which define what will be the accuracy of RTD value in this broadcast message. The accuracy will be coded as follows:

Table 5: Accuracy Range

1	0	Definition
0	0	1/16 bit accuracy
0	1	1/32 bit accuracy
1	0	1/64 bit accuracy
1	1	1/128 bit accuracy

The RTD accuracy will affect the amount of bits needed to indicate the RTD value. The following table describes the accuracy related to needed bits:

Table 6: Amount of RTD bits needed

Time Slots	Accuracy	Amount of Bits Needed
	1/16	12 bits
	1/32	13 bits
1	1/64	14 bits
	1/128	15 bits
	1/16	15 bits
8	1/32	16 bits
°	1/64	17 bits
	1/128	18 bits

RTD Drift Factors Present

This bit indicates whether the RTD Drift Factors are present in this broadcast message. If RTDs Present bit indicates that the RTD Values are not included into this broadcast message, the state of this bit should be ignored and the RTD Drift Factors are not present in this broadcast message.

- '0' RTD Drift Factors are not present in the message
- '1' RTD Drift Factors are present in the message

RTDs Present

This bit indicates whether RTD Values IE is present in this broadcast or not.

- '0' RTD Values IE not present
- '1' RTD Values IE present

Number of Neighbours

These 5 bits are indicating the amount of neighbours are in System Information Neighbour List according to which this broadcast message was created. The number of neighbours indicated here makes sure that MS can decode back this broadcast message IEs as they were originally sended. If the MS has received different amount of neighbours in System Information Neighbour List than indicated in this field in broadcast message, the MS should ignore this broadcast message.

Range: 1 – 32 Neighbours

4.1.1.2 Reference Time IE

The Reference Time IE gives information about the time when the RTD values in the broadcast message are calculated. The Reference Time IE contains the serving cell frame number modulo 16384 with 4 LSB bits omitted. The resolution of this Reference Time IE is thus 0.59 second. The Reference Time IE has 10 minutes periodicy. This IE is mandatory.

Range: 0 - 1023

4.1.1.3 Ciphering Serial Number IE

The Ciphering Serial Number IE contains the serial number used in ciphering process of the broadcast message. The IE contains two octets, MSB part and LSB part. The serial number range is 0 - 65535. This IE is conditional and it is present only if the ciphering flag is active in Message Structure Definition IE.

Table 7: Ciphering Serial Number IE

MSB	LSB
Ciphering Serial Number (8 bits)	Ciphering Serial Number (8 bits)

4.1.1.4 Time Slot Scheme IE

This information element contains information about the serving cell channel and neighbour channel time slot scheme. The list starts with Serving Cell Channel and the rest of the list is in the same order as the neighbours in the System Information Neighbour List. For each list member there is one bit reserved to indicate whether the channel has 156.25 bits time slot duration or 156/157 bits time slot duration. This field is varying length depending on amount of neighbours of System Information Neighbour List (max 32) and maximum length of this IE is 33 bits (1+32 bits). The Serving Cell Channel time slot scheme is always indicated as the first (MSB) element of this field. This IE is mandatory.

- '0' 156.25 bits time slot duration
- '1' 156/157 bits time slot duration

Table 8: Time Slot Scheme

Serving Cell Ch	Neigh Ch _{last}	 Neigh Ch₃	Neigh Ch₂	Neigh Ch ₁ (LSB)
0/1	0/1	 0/1	0/1	0/1

4.1.1.5 Neighbour Bitmap Definition IE

This IE defines which neighbours from System Information Neighbour List are included in this message. The IE is conditional and included only if Message Structure Definition IE's Neighbour List Map indicates the use of this Neighbour Bitmap Definition. The list is in the same order as the neighbours in the System Information Neighbour List, the last member of the list presented as the MSB element of this field. For each Neighbour List channel number there is one bit reserved to indicate whether the neighbour is included into this broadcast message. This field is varying length depending on the amount of neighbours of System Information Neighbour List (max 32) and maximum length of this IE is 32 bits.

- '0' Neighbour not included into this broadcast message
- '1' Neighbour included into this broadcast message

Table 9: Neighbour Bitmap Definition

Neigh Ch _{last}		Neigh Ch₃	Neigh Ch₂	Neigh Ch₁ (LSB)
0/1	•••		0/1	0/1

4.1.1.6 Sectored Channels Definition IE

This information element defines which neighbours in System Information Neighbour List that are included in this broadcast message are belonging to sectored BTSs. This IE is conditional and included only if Message Structure Definition IE's Sector Indicator is active. This field is varying length depending on amount of neighbours included into this broadcast message (max 32) and the maximum length of this IE is 33 bits (1+32 bits). The Serving Cell Channel sector indication is always indicated in MSB of this field and the neighbours are in same order as the neighbours in the System Information Neighbour List.

- '0' Channel not included to sectored BTS
- '1' Channel included to sectored BTS

Table 10: Sectored Channels Definition

Serving Ch	Neigh Ch _{last}	 Neigh Ch₃	Neigh Ch₂	Neigh Ch₁ (LSB)
0/1	0/1	 0/1	0/1	0/1

4.1.1.7 Sectored Channels BTS ID Definition IE

This information element defines what sectored channels are at the same BTS. The indication is done with three bits for each neighbour channel that is indicated to belong to sectored BTS (definition in Sectored Channels Definition IE). Belonging to the same BTS site is indicated with the same three bit binary ID, maximum 8 sectored BTS groups can be identified. This field is varying length depending on amount of sectored BTS in this broadcast message (max 33*3 bits = 99 bits when all 32 neighbours and the serving cell channel are belonging to some sector). This field follows the order of channels that have indicated to be belonging to sectored BTS in Sectored Channels Definition starting from the MSB. This IE is conditional and included only if Message Structure Definition IE's Sector Ind is active.

Table 11: Sectored Channels BTS ID Definition

2	1	0	Definition
0	0	0	Sectored BTS ID1
0	0	1	Sectored BTS ID2
0	1	0	Sectored BTS ID3
0	1	1	Sectored BTS ID4
1	0	0	Sectored BTS ID5
1	0	1	Sectored BTS ID6
1	1	0	Sectored BTS ID7
1	1	1	Sectored BTS ID8

Table 12: Sectored Channels BTS ID Definition

Indicated Sectored Neighbour _{last} (MSB)	 Indicated Sectored Neighbour ₃	Indicated Sectored Neighbour₂	Indicated Sectored Neighbour₁ (LSB)
Sec. BTS ID X	 Sec. BTS ID X	Sec. BTS ID X	Sec. BTS ID X
(3 bits)	(3 bits)	(3 bits)	(3 bits)

4.1.1.8 Sectored BTS Sync/Async Definition IE

This information element defines whether the indicated sectored BTS site contains synchronized or asynchronized channels. The sync/async is informed with one bit per sectored BTS ID. This field follows the order of IDs in Sectored Channels BTS ID Definition. This field is varying length depending on amount of sectored BTS ID in this broadcast message (max 8 bits). This IE is conditional and is included only if Message Structure Definition IE's Sector Ind is active.

- '0' Sectored BTS contains async channels
- '1' Sectored BTS contains sync channels

Table 13: Sectored BTS Sync/Async Definition

Sec BTS _{Last} (MSB)	•••	Sec BTS _{ID3}	Sec BTS _{ID2}	Sec BTS _{ID1}
0/1		0/1	0/1	0/1

4.1.1.9 Multiframe Offset Values IE

This information element defines the neighbour channel's 51 Multiframe Values. The 51 Multiframe Offset Values are describing the offset value related to the Serving Cell 51 Multiframe Value. This field is needed when co-channels must be identified from the real neighbour channels (included into System Information Neighbour List). Each 51 Multiframe Offset Value is 6 bits long denoting the offset value to the Serving Cell 51 Multiframe number. The 51 Multiframe Offset Values must be declared to all neighbours in this broadcast message and the values are in the same order as the neighbours in the System Information Neighbour List. The maximum length of this IE is 192 bits (32*6 bits). This IE is mandatory.

Table 14: 51 Multiframe Offset Values IE

51 MF Offset _{NbLast} (MSB)	 51 MF Offset	51 MF Offset Nb2	51 MF Offset Nb1 (LSB)
Offset Value	Offset Value	Offset Value	Offset Value
(6 bits)	 (6 bits)	(6 bits)	(6 bits)

4.1.1.10 BCC Definition IE

This information element defines the BBC (Base Station Color Code) values. The BCC is needed to know what training sequence is in use in the bursts in BCCH frequency. Each BCC is 3 bits long denoting the one of the 8 possible TSCs (Training Sequence Codes) possible to be used in bursts. BCC values must be declared to all neighbours in this message and the values are in the same order as the neighbours in the System Information Neighbour List. The maximum length of this IE is 96 bits (32*3 bits). This IE is mandatory.

Table 15: BCC Definition IE

BCC _{NbLast} (MSB)	 BCC _{Nb3}	BCC Nb2	BCC Nb1 (LSB)
BCC Value (3 bits)	 BCC Value (3 bits)	BCC Value (3 bits)	BCC Value (3 bits)

4.1.1.11 RTD Drift Factor Values IE

This IE contains the drift factor values for the Channel RTD Values included into this broadcast message. The RTD Drift Factor Values indicate the RTD drift in meters per second. Positive and negative RTD Drift Factors can be indicated as well as no drift value. This information element is conditional and included if the RTD Drift Factors Present bit in the Message Structure Definition IE is active and the RTDs Present bit is active. The RTD Drift Factors are included into the broadcast message with same conditions and in same order than the Channel RTD Values which are described in Channel RTD Values IE section (4.1.1.12). This IE should be ciphered if the ciphering is active. Each RTD Drift Factor Value is 5 bits long and the coding is as follows:

Table 16: RTD Drift Factor Values

Positive/Negative MSB	MSB	Codin	g Bits	LSB	Definition
3	3	2	1	0	
Don't care	0	0	0	0	0 m/s
0	0	0	0	1	+0.33 m/s
0	0	0	1	0	+0.66 m/s
0	0	0	1	1	+1 m/s
0	0	1	0	0	+1.33 m/s
0	0	1	0	1	+1.66 m/s
0	0	1	1	0	+2 m/s
0	0	1	1	1	+2.5 m/s
0	1	0	0	0	+3 m/s
0	1	0	0	1	+4 m/s
0	1	0	1	0	+5 m/s
0	1	0	1	1	+7 m/s
0	1	1	0	0	+9 m/s
0	1	1	0	1	+11 m/s
0	1	1	1	0	+13 m/s
0	1	1	1	1	+15 m/s
1	0	0	0	1	-0.33 m/s
1	0	0	1	0	-0.66 m/s
1	0	0	1	1	-1 m/s
1	0	1	0	0	-1.33 m/s
1	0	1	0	1	-1.66 m/s
1	0	1	1	0	-2 m/s
1	0	1	1	1	-2.5 m/s
1	1	0	0	0	-3 m/s
1	1	0	0	1	-4 m/s
1	1	0	1	0	-5 m/s
1	1	0	1	1	-7 m/s
1	1	1	0	0	-9 m/s
1	1	1	0	1	-11 m/s
1	1	1	1	0	-13 m/s
1	1	1	1	1	-15 m/s

Table 17: RTD Drift Factor Values IE

RTD Drift Factor		RTD Drift Factor	RTD Drift Factor	RTD Drift Factor
NbLast (MSB)		Nb3	Nb2	Nb1 (LSB)
RTD Drift Factor		RTD Drift Factor	RTD Drift Factor	RTD Drift Factor
Value (5 bits)	•••	Value (5 bits)	Value (5 bits)	Value (5 bits)

4.1.1.12 Channel RTD Values IE

This IE contains the channel RTD values relative to the serving BTS. The RTD value covers 1 or 8 time slot period with 1/16-1/128 bit accuracy. The 1 or 8 time slot period as well as 1/16-1/128 bit accuracy is defined in Message Structure Definition IE. The RTD values included here are conditional to the RTDs Present and Neighbour List Map (Message Structure Definition IE), Neighbour Bitmap Definition IE, Sectored Channels Definition IE, Sectored Channels BTS ID Definition and Sectored BTS Sync/Async Definition. This IE should be ciphered if the ciphering is active. The decision which BTS RTD value is included in this broadcast message has the following decision process:

- Channel RTD Values IE should not be included at all if RTDs Present bit (Message Structure Definition IE)
- Neighbours in this broadcast message are defined in Neighbour List Map (Message Structure Definition IE) and in case the Neighbour Bitmap Definition is active then the Neighbour Bitmap Definition IE declares the Neighbours included into this broadcast message.
- If Sector Indicator in Message Structure Definition IE is not active the RTD values are included for all neighbours in this broadcast message.
- If sector indicator in Message Structure Definition IE is active then the Neighbour channels that are not belonging to sectored BTS the RTD values are included directly according to neighbour list order.
- If sector indicator in Message Structure Definition IE is active then the Neighbour channels that are belonging to sectored BTS, the Sectored BTS ID values group the neighbour channels into the groups. If the Sectored BTS ID group is indicated to be synchronous then only one RTD value (decided by SMLC) per the Sectored BTS ID group is included into this broadcast message, if the Sectored BTS ID group is indicated to be asyncronous then all the neighbour channel RTDs belonging to the Sectored BTS ID group have to be included into this broadcast message.

(MSB) Varying Length (12-18 bits) (LSB)

Neighbour RTD (Last) (MSB)

Neighbour RTD (Last-1)

...

Neighbour RTD (2)

Neighbour RTD (1) (LSB)

Table 18: Channel RTD Value IE

The fields that are included into the Channel RTD Value IE may contain RTD values of neighbour channels and the RTD values of the sectored channels BTS ID. The RTD values should be included into this IE in following order:

- Starting from the last channel in the System Information Neighbour List that is included into this broadcast message.
- First are reported the neighbour channels that are not belonging to the Sectored Channels BTS ID groups and then the Sectored Channels ID groups from 1 up to 8 depending the amount of groups. See Annex B for example.

If the RTD value is invalid, following values in the RTD field are reserved for this indication (e.g. if invalid RTD value is indicated the MS shall discard the previous values):

Table 19: Invalid RTD Value Codes

Time Slots	Accuracy	Amount of Bits in RTD	Invalid RTD Code in
	1/16	12 bits	FFF
1	1/32	13 bits	1FFF
1	1/64	14 bits	3FFF
	1/128	15 bits	7FFF
	1/16	15 bits	7FFF
0	1/32	16 bits	FFFF
8	1/64	17 bits	1FFFF
	1/128	18 bits	3FFFF

This field is varying length depending on amount of Neighbour Channels included as well as amount of sectored cells and the nature (sync/async) of sectored cells. One RTD value has varying length of 12-18 bits indicating the amount on 1/16-1/128 bit durations over 1 time slot or 8 time slots. Maximum length of this IE is 576 bits (32*18 bits).

4.1.1.13 Serving Cell Location IE

This IE contains the Serving Cell Latitude/Longitude information. This IE should be ciphered if the ciphering is active. This IE is mandatory.

Serving Cell Latitude

This field indicates WGS-84 latitude with fixed length of 24 bits. Latitude value is coded according to 3GPP TS 23.032. This field is mandatory.

Table 20: Serving Cell Latitude

(MSB)	24 – 1	(LSB)
	Serving Cell Latitude (24 bits)	

Serving Cell Longitude

This field indicates WGS-84 longitude with fixed length of 24 bits. Latitude value is coded according to 3GPP TS 23.032. This field is mandatory.

Table 21: Serving Cell Longitude

(MSB)	24 – 1	(LSB)
	Serving Cell Longitude (24 bits)	

4.1.1.14 Relative Neighbour Location IE

This information element defines the location of Neighbour Channels (BTS) relative to Serving Cell Location. This IE should be ciphered if the ciphering is active. The fields are varying length depending on amount of neighbour channels and sectored cells included in this broadcast message. The location information per neighbour has two elements, Relative North and Relative East. The Relative North positive values indicate north direction, negative values indicate south direction from Serving Cell Location. The Relative East positive values indicate east direction and negative values indicate west direction from Serving Cell Location. The MSB bit in Relative North/East value is reserved for sign indication (positive=0, negative=1). The values are expressed in meters according to the accuracy resolution which is defined by Accuracy Range bits in Message Structure Definition IE. For example if the Accuracy Range is set to 20 km and there is 15 bits (1+14 bits) reserved for Relative North/East values this means 0.6 m accuracy for Relative North or East value. This IE is mandatory.

The amount of Relative North/East pairs depends on neighbours included in this broadcast message as well as the amount sectored cells since only one Relative North/East pair is included per Sectored BTS ID.

(MSB)

Relative North Value Neighbour (Last) (MSB)

Relative East Value Neighbour (Last)

Relative North Value Neighbour (Last-1)

Relative East Value Neighbour (Last-1)

...

Relative North Value (2)

Relative East Value (2)

Relative North Value (1)

Table 22: Relative Neighbour Location

The decision what Relative North/East Values are included in this broadcast message has following decision process:

Relative East Value (1) (LSB)

- Neighbours in this broadcast message is defined in Neighbour List Map (Message Structure Definition IE) and in case the Neighbour Bitmap Definition is active then the Neighbour Bitmap Definition IE declares the Neighbours included into this broadcast message.
- If Sector Indicator in Message Structure Definition IE is not active the Relative North/East Values are included in the same order as they are indicated in Message Structure Definition IE / Neighbour Bitmap Definition IE.
- If sector indicator in Message Structure Definition IE is active then the Neighbour channels that are not belonging to sectored BTS Relative North/East Values are included directly according to neighbour list order.
- If sector indicator in Message Structure Definition IE is active then the Neighbour channels that are belonging to sectored BTS, the Sectored BTS ID values group the neighbour channels into the groups. The Relative North/East Values are included in the broadcast message so that only one Relative North/East Value per Sectored BTS ID is included.

The fields that are included into the Relative Neighbour Location IE may contain the Relative North/East values of neighbour channels and the Relative North/East values of the sectored channels BTS ID groups. The RTD values should be included into this IE in following order:

- Starting from the last channel in the System Information Neighbour List that is included into this broadcast message.
- First are reported the neighbour channels that are not belonging to the Sectored Channels BTS ID groups and then the Sectored Channels ID groups from 1 up to 8 depending the amount of groups.
- The neighbour channel/BTS ID value will always contain Relative North value first and then Relative East value. The values are expressed in meters according to the Accuracy Range in the Message Structure Definition IE. See Annex B for example.

The bits available for Relative North/East Values can be calculated with following formula:

```
number of neighbours in System Info Neighbour List
z =
                 number of neighbours in this broadcast message
\mathbf{x} =
                 number of channels in sectors
a =
b =
                 number of BTS IDs
                 RTD accuracy (12-18 bits)
c =
                 Neighbour Bitmap used (yes=1, no=0)
\mathbf{w} =
                 RTDs Present (yes=1, no=0)
s =
                 RTD Drift Factors included (yes=1, no=0)
d =
                 bits per Relative Latitude / Longitude value
y =
                 Int(y) = (561-11*x-3*a-b-s*(c+d*5)*(x-a+b)-w*z)/(2*(x-a+b))
```

If the y doesn't go even, the bits that remain are used as one extra bit (extension bit) per one Relative North or East value in same order as the values are presented in this IE as long as there are remain bits available. See Annex B for example.

4.2 GPS Assistance Data Broadcast Message

The GPS Assistance Data message contents are defined in this clause. The GPS Assistance Data message is built so that it is fitted into a fixed length message not necessary occupying the whole message. In case that the fixed length message has less information elements than bits available then the rest of message is filled with fill bits. The information elements are in the order which is described in section 4.2.1 and no undefined spare bits are allowed between elements. The channel to broadcast the GPS Assistance Data message is CBCH over which the SMSCB DRX service is used. One SMSCB message has fixed information data length of 82 octets and the maximum length of GPS Assistance Data is 82 octets. MS can identify the LCS SMSCB message with Message Identifiers declared in 3GPP TS 23.041. Example of GPS Assistance Data Broadcast Message is in Annex C. In addition, an Integrity Monitor (IM) shall detect unhealthy (e.g., failed/failing) satellites. When an unhealthy (i.e., failed/failing) satellite is detected, the assistance data, including DGPS corrections, shall not be supplied for that particular satellite. If more satellites are unhealthy, the same can be done to exclude them from the final location calculation. Even when all satellites are healthy, the IM shall monitor the quality of the DGPS corrections. It shall make use of the pseudoranges derived by the DGPS reference receiver, correct them using the DGPS reference receiver-generated DGPS corrections, and compute a position from the corrected pseudo ranges. This computed position shall then be compared with the known, surveyed location of the DGPS reference receiver to compute a DGPS positioning error. Positioning errors which are excessive relative to DGPS expected accuracy levels shall be used to inform users of measurement quality via the UDRE parameter.

4.2.1 GPS Assistance Data Content

The GPS Assistance Data Message contents are defined in this clause. It contains three data sets: DGPS correction, ephemeris and clock correction, almanac and other data information. The empheris, clock correction, almanac and other data are obtained from GPS navigation message. It is built so that it fits into a fixed length message not necessarily occupying the whole message. In case that the fixed length message has less information elements than bits available then the rest of message is filled with fill bits.

This message is built to allow for broadcast rates that more closely match the time of applicability of the contained data. For example, with a 30-second rate for DGPS broadcast, mobile staion (MS) can effectively remove degration caused by SA. GPS subframes 1 through 3 (ephemeris and clock correction data) are contained in the same single broadcast message. With a 90-second rate, mobile stations (MS) can receive all visible ephemeris and clock correction data at twelve to eighteen minute intervals depending on number of visible satellites. Subframes 4 and 5 (almanac, ionospheric delay, and other more slowly changing data can be sent at another rate, such as once every several hours. By splitting the data into separate data sets (all based on the same single format), the data can be sent at rates that are correspond to its validity time and/or the desire to update the mobile stations within its network at a particular rate. The information elements (IEs) in the message are listed in Table 23 below.

Parameter Bits Resolution Range Units Occurrences Presence Ref Cipher 0 - 11 On/Off Cipher Ciphering 1 0 - 11 M ---Control Key Flag Ciphering Serial Number 16 0 - 65535 С 638 Μ Data

Table 23: Information Elements of GPS Assistance Data message

Cipher Control IE

This information element contains two bits indicating the ciphering properties of the received message. This IE is mandatory.

Cipher On/Off

This IE indicates whether this broadcast message has been ciphered or not. A value of "0" indicates that ciphering is off, while a value of "1" indicates that ciphering is active. The Data IE is ciphered if ciphering is active.

Ciphering Key Flag

The MS always receives two (2) cipher keys during the location update procedure. One of the keys is time-stamped to be current one and the other is time-stamped to be the next one. Thus, the MS always has two cipher keys in memory. The Cipher Key Change Indicator in this broadcast message instructs the MS whether to use current or next cipher key for deciphering the received broadcast message. The MS shall interpret this IE as follows:

- **Ciphering Key Flag**(previous message) = **Ciphering Key Flag**(this message) => Deciphering Key not changed
- Ciphering Key Flag(previous message) <> Ciphering Key Flag(this message) => Deciphering Key changed

Ciphering Serial Number IE

The Ciphering Serial Number IE contains the serial number used in ciphering process of the broadcast message. The IE contains two octets, MSB part and LSB part. The serial number range is 0 - 65535. This IE is conditional and it is present only if the ciphering flag is active in Cipher Control IE.

Table 24: Ciphering Serial Number IE

MSB	LSB
Ciphering Serial Number (8 bits)	Ciphering Serial Number (8 bits)

Data IE

The Data IE contains the GPS assistance data included in the broadcast message. The Data IE may contain DGPS Correction Data (4.2.1.1), Emphemeris and Clock Correction Data (4.2.1.2) or Almanac and Other Data (4.2.1.3). The Data IE content is indicated with the SMSCB message identifier specified in TS 23.041 and TS 23.041. When ciphering is active (indicated with Ciphering Control Flags), the ciphering will apply only to the Data IE element. This IE is mandatory.

4.2.1.1 DGPS Correction Data

This subsection describes the contents of the broadcast message for differential corrections. The message contents are based on a Type-1 message of version 2.2 of the RTCM-SC-104 recommendation for differential service [15]. This format is a standard of the navigation industry and is supported by all DGPS receivers. For a 11 satellites, the length of the broadcast message is 82 octets, which also is the maximum length of an SMSCB message. The information elements (IEs) in the message are listed in Table 26 below. If any of the conditional elements (Ciphering Serial Number, BTS Clock Drift, FN, TN and BN) are not included to the message, spare bits will be transmitted instead of these fields. The spare bits have equal length to the conditional IE, so that the message structure is unchanged (see Annex C). The spare bits are set to '0'.

Parameter Bits Resolution Range Units **Occurrences Precence** Ref **GSM Time Present** 1 0 - 1 M 4.2.1.2 **BTS Clock Drift Present** 1 0 - 1 Μ 4.2.1.3 4.2.1.4 12.5x10⁻³ С **BTS Clock Drift** 4 ±0.1 1 usec/sec 4.2.1.5 48 Reference Location 1 M Degrees 22 0-524287 1 С frames Reference ΤN 3 0 - 7timeslots 1 С 4.2.1.6 time 0 - 156BN 8 bits 1 С **GPS TOW** 20 1 0-604794 М sec 1 Status/Health 3 1 4.2.1.7 0 - 7M N SAT 4 ---1 - 12---1 С 4.2.1.8 Satellite ID 6 1 - 64 ---IODE 8 0 - 239---**UDRE** 2 ---0 - 3---**DGPS** 12 **PRC** 0.32 ±655.34 m N_SAT С 4.2.1.9 Corrections **RRC** 8 0.032 ±4.064 m/sec Delta PRC2 8 1 ±127 m Delta RRC2 4 0.032 ±0.224 m/sec

Table 26: DGPS Correction Data

4.2.1.1.1 GSM Time Present IE

This field indicates whether or not GSM air-interface timing information values for the serving cell are present in this message. The MS shall interpret a value of "1" to mean that GSM timing information values (FN,TN and BN) are present, and "0" to mean that only the GPS TOW field value is provided. This field is mandatory.

4.2.1.1.2 BTS Clock Drift Present IE

This IE is indication whether this broadcast message contains BTS Clock Drift IE value or not. The length of this IE is one bit. The value '1' indicates that BTS Clock Drift IE value is present, '0' indicates that the IE value is not present in this proadcast message. This IE is mandatory.

4.2.1.1.3 BTS Clock Drift IE

This IE provides an estimate of the drift rate of the BTS clock relative to GPS time. It has units of μ sec/sec (ppm) and a range of ± 0.1 . This IE aids the MS in maintaining the relation between GPS and cell timing over a period of time. The value of the clock drift is valid starting at the time contained in the Reference Time IE. A positive value for BTS Clock Drift indicates that the BTS clock is running at a greater frequency than desired. This IE is conditional and value is included in the message if BTS Clock Drift Present IE flag is '1'.

4.2.1.1.4 Reference Location IE

The Reference Location field contains a 2-D location (without uncertainty) specified as per 3GPP TS 23.032. The purpose of this field is to provide the MS with a priori knowledge of its location in order to improve GPS receiver performance.

4.2.1.1.5 Reference Time IE

This IE specifies the relationship between GPS time and air-interface timing of the BTS transmission in the serving cell. The **GPS TOW** (time-of-week) has a one-second resolution with a range of 0 to 604799. The **FN**, **TN**, and **BN** IEs are respectively the GSM frame number, timeslot number, and bit number of the BTS transmissions for the serving cell that occur at that GPS time. The frame number FN is modulo- 2^{19} (0 – 524287) and the MS shall resolve the ambiguity by interpreting the frame to be as near as possible to the current frame of the serving BTS. The **GPS TOW** IE is mandatory. The **FN**, **TN**, and **BN** IEs are conditional and the values are present only when GSM Time Present bit is '1'.

4.2.1.1.6 Status/Health IE

This IE indicates the status of the differential corrections contained in the broadcast message. It is equivalent to the "Station Health" IE in the common header for all reference station messages specified in [15]. The values of this IE and their respective meanings are shown below in Table 25. This IE is mandatory.

Code Indication UDRE Scale Factor = 1.0 000 001 UDRE Scale Factor = 0.75 010 UDRE Scale Factor = 0.5 UDRE Scale Factor = 0.3 011 100 UDRE Scale Factor = 0.2 101 UDRE Scale Factor = 0.1 110 No data available 111 Data is invalid - disregard

Table 25: Values of Correction Status

The first six values in this IE indicate valid differential corrections in the broadcast message. When using the corrections values described below, the "UDRE Scale Factor" value is applied to the UDRE values contained in the message. The purpose is to indicate an estimate in the amount of error in the corrections.

The value "110" indicates that the source of the differential corrections (e.g., reference station or external DGPS network) is currently not providing information. The value "111" indicates that the corrections provided by the source are invalid, as judged by the source. In either case, the broadcast message shall contain no differential corrections. All MS that read the broadcast message shall contain the appropriate logic to ignore any data IEs following a Correction Status IE having a value of "110" or "111".

4.2.1.1.7 N_SAT IE

This IE indicates the number of satellites (N_SAT) for which differential corrections are available. The maximum number of satellites that can be included into the message is 12. This IE is conditional and included if Correction Status IE value is not 110 or 111.

4.2.1.1.8 DGPS Corrections IE

This IE contains GPS differential correction data. Each element described below will appear N_SAT times in this message, once for each satellite for which corrections are available. This IE is conditional and included if Correction Status IE value is not 110 or 111.

Satellite ID

This IE identifies the satellite for which the corrections are applicable. This value is the same as the PRN number provided in the navigation message transmitted by the particular satellite. The range is 0 to 31, with 0 indicating satellite number 32 as per[15].

IODE

This IE is the sequence number for the ephemeris for the particular satellite. The MS can use this IE to determine if new ephemeris is used for calculating the corrections that are provided in the broadcast message. This eight-bit IE is incremented for each new set of ephemeris for the satellite and may occupy the numerical range of [0, 239] during normal operations. For more information about this field can be found from [15].

User Differential Range Error (UDRE)

This IE provides an estimate of the uncertainty $(1-\sigma)$ in the corrections for the particular satellite. The value in this IE shall be multiplied by the UDRE Scale Factor in the common Corrections Status IE to determine the final UDRE estimate for the particular satellite. The meanings of the UDRE values are described in Table 27 below.

Table 27: Values of UDRE

Value	Indication
00	UDRE ≤ 1.0 m
01	1.0 m < UDRE ≤ 4.0 m
10	4.0 m < UDRE ≤ 8.0 m
11	8.0 m < UDRE

Each UDRE value shall be adjusted based on the operation of an Integrity Monitor (IM) function which exists at the network (SMLC, GPS server, or reference GPS receiver itself). Positioning errors derived at the IM which are excessive relative to DGPS expected accuracy levels shall be used to scale the UDRE values to produce consistency.

Pseudo-Range Correction (PRC)

This IE indicates the correction to the pseudorange for the particular satellite at the reference time, t_0 . As mentioned above, this reference time is the GPS TOW. The value of this IE is given in meters (m) and the resolution is 1. The method of calculating this IE are described in [15].

Pseudo-Range Rate Correction (RRC)

This IE indicates the rate-of-change of the pseudorange correction for the particular satellite, using the satellite ephemeris identified by the IODE IE. The value of this IE is given in meters per second (m/sec) and the resolution is 0.032. For some time $t_1 > t_0$, the corrections are estimated by

$$PRC(t_1, IODE) = PRC(t_0, IODE) + RRC(t_0, IODE) \cdot (t_1 - t_0),$$

and the MS uses this to correct the pseudorange it measures at t_1 , $PR_m(t_1)$, by

$$PR(t_1, IODE) = PR_m(t_1, IODE) + PRC(t_1, IODE).$$

Delta Pseudo-Range Correction 2 (Delta PRC2)

This IE indicates the difference in the pseudorange correction between the satellite's ephemeris identified by IODE and the previous ephemeris two issues ago IODE –2. The value of this IE is given in meters (m) and the resolution is 0.32. The method of calculating this IE are described in [15].

Delta Pseudo-Range Rate Correction 2 (Delta RRC2)

This IE indicates the difference in the pseudorange rate-of-change correction between the satellite's ephemeris identified by IODE and IODE-2. The value of this IE is given in meters per second (m/sec) and the resolution is 0.032. For some time $t_1 > t_0$, the corrections for IODE-2are estimated by

$$PRC(t_1,IODE-2) = [PRC(t_0,IODE) + DeltaPRC(t_0,IODE)] + [RRC(t_0,IODE) + DeltaRRC(t_0,IODE)] \cdot (t_1 \cdot t_0) \; , \\$$

and the MS uses this to correct the pseudorange it measures at t₁ using ephemeris IODE-2, PR_m(t₁, IODE-2), by

$$PR(t_1, IODE-2) = PR_m(t_1, IODE-2) + PRC(t_1, IODE-2)$$
.

If there is not an ephemeris set for a currently visible satellite that is two issues old, then the parameters Delta PRC2 and Delta RRC2 are both set to zero.

4.2.1.2 Ephemeris and Clock Correction Data

This subsection describes the contents of the Data for ephemeris and clock corrections of a particular satellite. These IE fields are extracted from the subframes 1 to 3 of the GPS navigation message. They are listed in Table 28.

Table 28: Ephemeris and Clock Correction Data (per-satellite fields - (1) = Positive range only)

Parameter	Bits	Resolution	Range	Units	Occurrences	Presence
Transmission TOW	20	1	0 – 604799	seconds	1	M
SVID/PRNID	6 ⁽¹⁾		0 – 63		1	М
TLM Message	14		0 - 16383		1	М
TLM Reserved (C)	2		0 - 3		1	М
HOW	22		0 - 4194303		1	М
WN	10		0 – 1023	weeks	1	М
C/A or P on L2	2		0 – 3	Boolean	1	М
URA Index	4		0 – 15	Boolean	1	М
SV Health	6		0 – 63	Boolean	1	М
IODC	10 ⁽¹⁾		0 – 1023		1	М
L2 P Data Flag	1		0 – 1	Boolean	1	М
SF1 Reserved	87		Ful I Range		1	М
T _{GD}	8	2 ⁻³¹	-128 – 127	seconds	1	M
t _{oc}	16 ⁽¹⁾	2 ⁴	0 - 604784	seconds	1	М
Af ₂	8	2 ⁻⁵⁵	-128 – 127	sec/sec ²	1	М
Af ₁	16	2 ⁻⁴³ 2 ⁻³¹	-32768 – 32767	sec/sec	1	M
Af ₀	22	2 ⁻³¹	-2097152 –	seconds	1	M
			2097151			
C_{rs}	16	2 ⁻⁵ 2 ⁻⁴³	-32768 – 32767	meters	1	М
Δn	16	2 ⁻⁴³	-32768 – 32767	semi-	1	М
				circles/sec		
M ₀	32	2 ⁻³¹	-2147483648 –	semi-	1	М
			2147483647	circles		
C_{uc}	16	2 ⁻⁵	-32768 – 32767	meters	1	М
Е	32 ⁽¹⁾	2 ⁻³³	0 - 4294967295		1	М
Cus	16	2 ⁻²⁹	-32768 – 32767	radius	1	М
(A) ^{1/2}	32 ⁽¹⁾	2 ⁻¹⁹	0 - 4294967295	meters ^{1/2}	1	М
t _{oe}	16 ⁽¹⁾	2 ⁴	0 - 604784	seconds	1	М
Fit Interval Flag	1		0 – 1	Boolean	1	М
AODO	5	900	0 – 31	seconds	1	М
C _{ic}	16	2 ⁻²⁹	-32768 – 32767	radians	1	М
OMEGA ₀	32	2 ⁻³¹	-2147483648 –	semi-	1	M
			2147483647	circles		
C _{is}	16	2 ⁻²⁹ 2 ⁻³¹	-32768 – 32767	radians	1	М
i ₀	32	2 ⁻³¹	-2147483648 –	semi-	1	М
			2147483647	circles		
C _{rc}	16	2 ⁻²⁹ 2 ⁻³¹	-32768 – 32767	meters	1	M
ω	32	2 ⁻³¹	-2147483648 –	semi-	1	М
			2147483647	circles		
OMEGAdot	24	2 ⁻⁴³	-8388608 –	Semi-	1	М
			8388607	circles/sec		
ldot	14	2- ⁴³	-8192 – 8191	Semi-	1	М
				circles/sec		
Spares/zero fill	20				1	М

Transmission TOW

This field indicates the approximate GPS time-of-week when the message is broadcast. The MS should interpret this field as a very coarse estimate of the current time.

SVID/PRNID

The satellite ID of the data from which this signal was obtained.

Rest of Fields

The rest of fields are defined as in Figure 20-1 of [16].

4.2.1.3 Almanac and Other Data

This subsection describes the contents of the Data for ionospheric delay, UTC offset, and Almanac. These IE fileds are extracted from the subframes 4 and 5 of the GPS navigation message, excluding the parity bits and other redundant bits. They are listed in Table 29.

Table 29: Almanac and Other Data

Parameter	Bits	Resolution	Range	Occurrences	Presence
Transmission TOW	20	1	0 - 604799	1	М
SV Mask	32			1	М
LSB TOW	8	1	0 - 255	1	М
SFID 0	1	1	0 – 1		
Data ID	2				
Page No.	6	1	1 - 25	Repeat three	
Word 3	16	COSP	COSP	times:	
Word 4	24	COSP	COSP	Each	
Word 5	24	COSP	COSP	corresponds	
Word 6	24	COSP	COSP	to a different	M
Word 7	24	COSP	COSP	page no. as	
Word 8	24	COSP	COSP	described in	
Word 9	24	COSP	COSP	Table 29	
Word 10	22	COSP	COSP		
Spares/zero fill	5			1	М

Transmission TOW

This field indicates the approximate GPS time-of-week when the message is broadcast. The MS should interpret this field as a very coarse estimate of the current time.

SV Mask

This field indicates the satellites that contain the pages being broadcast in this data set.

LSB TOW

This field indicates the least significant 8 bits of the TOW. See [16], Figure 20-2.

COSP

Format Conditional on Subframe ID and Page Number. See [16], section 20.3.3.5, Figure 20-1.

SFID 0

This one bit field conveys the least significant bit of the SubFrame(SF) ID for which the following word 3 through word 10 data applies. Zero indicates subframe ID = 4, and One indicates Subframe ID = 5.

Data ID

Indicates the Data ID field contained in the indicated subframe, word 3, most significant 2 bits, as defined by [16].

Page No.

Six-bit field indicates the Page ID of the indicated subframe for which the following Word 3 through Word 10 data applies. The page field and SFID field define the data content and format for the following word 3 through word 10 data fields as defined by [16].

Word 3 through Word 10

Information bits (16, 22 or 24) that are contained in the respective words of the indicated subframe and page, excluding 2 bit "t" from Word 10. See reference [16] for more information.

Each broadcast Almanac and Other Data message contains three subframes of information. All three of subframe pages in this data set can be from the same subframe ID (all from subframe 5 for example), or a mixed set containing some subframe 4 and some subframe 5 data.

Table 29 shows the subframe and page numbers corresponding to the Almanac, SV Health, and Iono / UTC Correction data. A total of 35 subframes must be broadcast if all the information is to be provided to the MS. Given that three subframes worth of content can be delivered per broadcast message, it will take only 12 broadcast messages to deliver the entire data set shown in Table 29. If the data listed in Table 29 is broadcast at the rate of approximately once per four hours, one Almanac and Other Data message must be broadcast on average every 20 minutes. An alternate approach is to broadcast the 12 messages as a set closely together in time, but with four-hour duration between sets. Note that the four-hour figure is only used to illustrate the concept, and a shorter or longer period may be used instead.

It is possible to broadcast other data contained in Subframes 4 and/or 5 not shown in Table 29. The format of the message remains the same, only the particular page of the desired data needs to be set properly. The contents of words 3 through 10 also need to be set as described in [16]. Using this format, it provides maximum compatibility for future expansion to include other data in subframes 4 and 5 not shown in Table 30 or [16].

Table 30: - Mapping of Almanac, Health, Iono, and UTC Data to Subframe Number and Page Number

Data Type	Subframe	Page(s)
Almanac Data (SV1 – 24)	5	1 - 24
Almanac Data (SV25 – 32)	4	2, 3, 4, 5, 7, 8, 9, 10
SV Health (SV1 – 24)	5	25
SV Health (SV25 – 32)	4	25
Iono/UTC Corrections	4	18

Annex A (informative): Overview of Broadcast Assistance for E-OTD and GPS

This annex presents an overview of the functionality and requirements for broadcasting assistance information for GPS and E-OTD in GSM networks. Potential impacts to other services are also described.

A.1 General

The E-OTD and GPS assistance information may be broadcast over the SMSCB service. The SMSCB DRX service is used to forecast the occurrences of the broadcast messages. The E-OTD and GPS broadcasts are independent of each other, have own SMSCB message identifiers and are broadcast on the demand of the characteristics of the E-OTD and GPS. In the network side, the SMLC is responsible for gathering the information, constructing the broadcast messages and ciphering a part of the message, if necessary. The SMLC also maintains the deciphering keys that MS requests with MO-LR. The deciphering keys are location area specific.

SMSCB messages can be received when MS is in idle mode. When MS is in dedicated mode the same information that was received in idle mode via broadcast channel may be requested by MS via point-to-point messaging.

A.2 E-OTD Assistance Broadcast

The information that is broadcast for E-OTD assistance is used in MS-based E-OTD to help the MS measure neighbour BTSs and compute its own position. The broadcast message is built so that it has always a fixed length of 82 octets, which is the size of one SMS Cell Broadcast (SMSCB) message. The information elements are scalable according to the number of neighbour BTSs and the amount of sectored channels.

In general, the following information is included in a broadcast E-OTD assistance message:

- Reference Time
- Neighbour Channel Time Slot Scheme
- Information about sectored neighbour channels
- Neighbour channel 51 Multiframe Offset values
- Neighbour channel BCC values
- RTD Drift Factor values (ciphered if active)
- Neighbour channel RTD values (ciphered if active)
- Serving cell and neighbour cell location information (ciphered if active)

The system information message that is received in idle mode contains the neighbour channel information. The E-OTD SMSCB message refers to this system information neighbour list so that there is indication which neighbours in the system information neighbour list are included in the broadcast message. The neighbour channel RTD values, serving cell location and neighbour cell location information may be ciphered.

Based on the information in the broadcast message and the E-OTD measurements done by MS, MS is capable to calculate its position. MS that is not capable to calculate its position itself may receive the SMSCB messages and use the unciphered contents to help the synchronization to the neighbour channels.

Most information contained in the E-OTD broadcast message is static. However, the RTD values change relatively often due to the drift in unsynchronized BTS clocks. The duration of validity of RTD values will affect the location accuracy calculated by MS. The RTD update rate is a function of BTS clock stability and required location accuracy from the operator and may be specified by the operator.

A.3 GPS Assistance Broadcast

Broadcast DGPS Data

The main content of the broadcast message for GPS assistance is DGPS corrections. This information is used in MS-based GPS positioning to improve the accuracy of the position result. Some background information for DGPS broadcast is presented in this section. Requirements on the GSM network for broadcasting DGPS corrections are also discussed.

In good signal environments, the primary determinant of position accuracy for GPS is the intentional degradation of the GPS satellite clocks, known as *selective availability* (SA). Another contributor to the error budget is unmodeled atmospheric delay. The techniques used to correct these error sources are collectively known as *differential GPS* (DGPS). These methods involve locating one or more reference receivers at known locations and observing the visible satellite signals. These receivers essentially solve the inverse GPS problem – find differences from the expected measurements at the known position. The accuracy of the DGPS corrections is inversely proportional to the distance from the reference location. The inaccuracy is caused by changes in the geometry and visibility of the satellite constellation. For most applications, however, the corrections are valid for receivers within a 200-400 km radius of the reference station.

One noteworthy characteristic of the DGPS corrections is that they have a short time constant compared to other GPS information such as satellite ephemeris. Once a correction model is computed, its accuracy degrades over time. This is mainly due to the time-varying nature of the SA imposed on the satellite signals. The duration of validity of a set of differential corrections depends on the accuracy requirements of the user or application, but in general the corrections must be updated at least every 30 seconds.

The fact that DGPS corrections are valid for large areas but require frequent update make them very suitable for delivery over a GSM broadcast channel such as SMSCB. This broadcast strategy is used by other DGPS sources, such as FM broadcast stations and geostationary satellites (WAAS, EGNOS, and MSAS). However, broadcasting the DGPS corrections in the GSM network has a clear advantage over other sources. This is mainly due to the fact that GSM broadcast exploits the existing reliable data link between the GPS-capable MS and the GSM network. In the other methods, the MS must capture the DGPS information from another source and therefore pays a price in power consumption, complexity, or both.

The format used for GSM broadcast of DGPS corrections includes a list of satellites visible at a nearby reference location, the correction in the range measurement for each satellite, and the rate-of-change of the range correction. In addition, an allowance is made for adding correction differences (i.e., Δ PRC and Δ RRC values) for multiple copies of the GPS ephemeris, to reduce the network traffic flow. Other information includes satellite health status and a reference GPS time for the corrections. The total amount of DGPS information is 48 bits (6 octets) per satellite with 80 bits (10 octets) of overhead information. The total message size for 12 visible satellites is 82 octets, which will fit within a single SMSCB message.

Broadcast Other Data

The contents of the other broadcast GPS Assiatance Message data sets are ephemeris and clock correction, as well as almanac and other data. This information can be used by the GPS receiver integrated with MS to improve the signal acquisition time and sensitivity, to recover GPS time and to obtain Ephemeris, clock correction, UTC offset, Ionospheric delay, and Almanac data. For example, the ephemris data set may be broadcast every 90 seconds, and Almanac may be broadcast once every serveral hours. The mobile station which does not require E-OTD and/or DGPS assistance can wake up at 90 second intervals, download these data, and then go back to sleep. This broadcast message can assist mobile station in idle mode to acquire GPS satellites with improved sensitivity and perform GPS time recovery without point-to-point communication, therefore improving the time to the first fix and reducing the point-to-point message traffic. The message can be provided within a single SMSCB message.

A.4 Impact on Other Services

Latency

The main impact is due to latency requirements for delivery of the DGPS and E-OTD assistance information. Both the DGPS corrections and the RTD values are valid for relatively short periods of time, and must be delivered in a timely

manner. Thus, the service is sensitive to delays such as buffering broadcast SMSCB messages. The Reference Time in the broadcast messages and the drift factors can be used to compensate latency.

The Ephemeris and Clock Correction data set needs to be broadcast once every 90 seconds. The period for broadcasting the data set is chosen to provide the entire ephemeris (three subframes) in a reasonable amount of time. For 8 satellites, it would take 12 minutes. The Almanac and Other Data data set can be broadcast every several hours. To deliver the entire data set within 6 minutes, 12 broadcasts with a 30 second rate are required. It can also be broadcast at a much slower rate. For instance, for a 20 minute rate, the data set can be delivered to the mobile station every 4 hours.

Capacity

The SMSCB used for LCS uses the basic CBCH or extended CBCH. The support of E-OTD and/or DGPS broadcast needs capacity related to broadcast message characteristics (RTD/DGPS validity). The SMSCB DRX service also needs to schedule a message that is sent once per schedule period. The maximum schedule period is 48 SMSCB message slots.

Example of capacity scenario:

- The basic CBCH uses the same physical resource as SDCCH/4 (sub channel 2) or SDCCH/8 (sub channel 2). If SMSCB service is supported in basic CBCH it occupies 1/4 of SDCCH capacity when using SDCCH/4 and 1/8 of SDCCH capacity when using SDCCH/8
- The basic CBCH capacity is 1 SMSCB message per 2 seconds
- Both DGPS and E-OTD broadcast is assumed to be once per 30 second s and the Ephemeris and Almanac messages are assumed to be once per 90 seconds or longer (capacity is 15 SMSCB messages per 30 seconds)
- Schedule period is 45 (=45 x 2 seconds=90 seconds). If SMSCB DRX service is used for other services in SMSCB, the one SMSCB DRX schedule message per schedule period is needed to support all services
 - => LCS needs 2/15 + 1/45 of SMSCB capacity plus one schedule message every 90 seconds for delivering assistance data for both E-OTD and GPS methods.

Annex B (informative): Example of E-OTD Assistance Data Broadcast Message

This example describes how the message is built when following neighbour cell information is enclosed into SMSCB broadcast message:

- All neighbours (1-19) from System Information Neighbour List is included into one broadcast message
- The neighbours 1, 2, 3, 7, 8, 9, 11, 12, 13, 16, 17 and 19 are belonging to sectored BTS and following channels are in the same groups: (1, 2, 3), (7, 8, 9), (11, 12, 13) and (16, 17, 19). Serving cell channel is not belonging to sectored BTS.
- The channels belonging to sectored BTS are syncronized
- The accuracy range is 15 km, and ciphering is active
- The 51 Multiframe Value is included, the RTD range is 1 time slot and the RTD accuracy in 1/32 bit
- BTS network is not syncronized
- RTD Drift Factors are not included into message

NOTE: There are 15 remain bits for Relative Location Values and the 15 bits are used for Relative North or East extention bits. These bits are added to Nb18 North, Nb18 East, Nb15 North, Nb15 East, Nb14 North, Nb14 East, Nb10 North, Nb10 East, Nb6 North, Nb6 East, Nb5 North, Nb5 East, Nb4 North, Nb4 East and ID4 North.. These have 8 bits and the rest have 7 bits for relative location value.

Cipher Cipher Accuracy Range All Neighbours ASB(000LSB MSB(000LSB MSB	8	7	6	5	4	3	2	1	
MSB(11)		Key Ind							Octet1
Reference Time		of Neigh	Present	Drift Factors Present			Range	Ind On	Octet2
Ciphering Serial Number (MSB, bits 15-13)				ne		Numbe	r of Neigh (C	001)LSB	Octet3
Ciphering Serial Number (bits 12-5)		ring Serial N	umber	3)	Referenc	e Time (LSE	3, bits 4-0)		Octet4
Serv Cell (MSB)& Nb ₁₉₋₁₈	(IVI	3B, DIIS 13-		ering Serial N	Number (bits	12-5)			Octet5
Time Slot Scheme Nb ₁₇₋₁₀									Octet6
Sectored Channels Serv Cell & Nb ₁₉₋₁₄ (0101100)		, , ,	7		heme Nb ₁₇₋₁	0	,		Octet7
Sec Ch BTS ID4 Nb19									
Sec Ch BTS ID4 Nb19		Sector			•	·		Slot Scheme	
MSB(011)LSB	Sec	^h BTS ID4		ed Channels			nels		
Nb13 MSB(01)	N	//SB(011)LS	В	DL DTO 15 :	Nb	₅₋₁ (00111)L	SB	NU. 47	
BTS ID2	Nb13 M	ISB(01)	N	/ISB(011)LS	В	N	/ISB(011)LS	В	
MSB(001)LSB	BTS ID2 Nb9							BTS ID3	Octet13
Sec Ch BTS ID1								_	Octet14
S1MF Offset Value Nb19 (MSB)	Sec Ch	BTS ID1	Sec	Ch BTS ID1	Nb2	Sec	Ch BTS ID1	Nb3	Octet15
51MF Offset Value Nb18 (MSB) 51MF Offset Value Nb19 (LSB) Octet17 51MF Offset Value Nb16 (MSB LSB) 51MF Offset Value Nb16 (MSB) 51MF Offset Value Nb16 (MSB) 51MF Offset Value Nb15 (MSB) 51MF Offset Value Nb14 (MSB) 51MF Offset Value Nb15 (LSB) Octet20 51MF Offset Value Nb14 (MSB) 51MF Offset Value Nb15 (LSB) Octet21 Offset Value Nb12 (MSB) 51MF Offset Value Nb11 (MSB) 51MF Offset Value Nb12 (LSB) Octet22 51MF Offset Value Nb10 (MSB) 51MF Offset Value Nb11 (LSB) Octet23 51MF Offset Value Nb10 (MSB) 51MF Offset Value Nb11 (LSB) Octet24 Offset Value Nb8 (LSB) 51MF Offset Value Nb7 (MSB) 51MF Offset Value Nb8 (LSB) Octet25 51MF Offset Value Nb7 (MSB) 51MF Offset Value Nb8 (LSB) Octet26 51MF Offset Value Nb7 (MSB) 51MF Offset Value Nb7 (LSB) Octet27 Offset Value Nb4 (MSB)				Sync	Sync	Sync	Sync	Sec Ch BTS ID1 Nb1	Octet16
Offset Value Nb16 (MSB) 51MF Offset Value Nb15 (LSB) 51MF Offset Value Nb13 (MSB LSB) 51MF Offset Value Nb14 (LSB) 51MF Offset Value Nb14 (LSB) 51MF Offset Value Nb11 (MSB) 51MF Offset Value Nb11 (MSB) 51MF Offset Value Nb10 (MSB) 51MF Offset Value Nb11 (LSB) 51MF Offset Value Nb10 (MSB) 51MF Offset Value Nb11 (LSB) 51MF Offset Value Nb10 (LSB) 51MF Offset Value Nb7 (MSB) 51MF Offset Value Nb8 (LSB) 51MF Offset Value Nb7 (MSB) 51MF Offset Value Nb7 (LSB)		51MF Offs	set Value Nb	18 (MSB)		51MF Off	set Value N	` /	Octet17
S1MF Offset Value Nb14 (MSB) S1MF Offset Value Nb15 (LSB) Octet20	Offset Value Nb16		51MF	Offset Value	e Nb17 (MSI	3 LSB)		Offset Value Nb18	Octet18
51MF Offset Value Nb13 (MSB LSB) 51MF Offset Value Nb12 (MSB) 51MF Offset Value Nb14 (LSB) 51MF Offset Value Nb11 (MSB) 51MF Offset Value Nb10 (MSB LSB) 51MF Offset Value Nb10 (MSB LSB) 51MF Offset Value Nb10 (MSB LSB) 51MF Offset Value Nb7 (MSB) 51MF Offset Value Nb7 (LSB)	51MF Offs		` ′		51MF Off				
Offset Value Nb12 (MSB) 51MF Offset Value Nb11 (MSB) 51MF Offset Value Nb10 (MSB) 51MF Offset Value Nb10 (MSB) 51MF Offset Value Nb11 (LSB) Octet23 51MF Offset Value Nb10 (MSB LSB) 51MF Offset Value Nb11 (LSB) Octet24 Offset Value Nb8 (MSB) 51MF Offset Value Nb9 (MSB LSB) Octet24 Offset Value Nb8 (LSB) 51MF Offset Value Nb7 (MSB) 51MF Offset Value Nb8 (LSB) Octet25 51MF Offset Value Nb6 (MSB) 51MF Offset Value Nb7 (LSB) Octet25 Octet26 51MF Offset Value Nb6 (MSB) 51MF Offset Value Nb7 (LSB) Octet27 Offset Value Nb4 (MSB) Nb6 (LSB)	E41.75	51MF Offs			NI-40 (140)		set Value NI		
51MF Offset Value Nb10 (MSB) 51MF Offset Value Nb9 (MSB LSB) 51MF Offset Value Nb9 (MSB LSB) 51MF Offset Value Nb9 (MSB LSB) 51MF Offset Value Nb10 (LSB) 51MF Offset Value Nb7 (MSB) 51MF Offset Value Nb7 (MSB) 51MF Offset Value Nb7 (MSB) 51MF Offset Value Nb7 (LSB)	Offset Value Nb12		51MF	Offset Value	,	,		Offset Value Nb14	Octet21
51MF Offset Value Nb9 (MSB LSB) 51MF Offset Value Nb8 (MSB) 51MF Offset Value Nb10 (LSB) 51MF Offset Value Nb7 (MSB) 51MF Offset Value Nb7 (MSB) 51MF Offset Value Nb6 (MSB) 51MF Offset Value Nb7 (LSB) 51MF Offset Value Nb6 (MSB) 51MF Offset Value Nb7 (LSB)	51MF Offs				51MF Off		. ,		
Offset Value Nb8 (MSB) 51MF Offset Value Nb7 (MSB) 51MF Offset Value Nb6 (MSB) 51MF Offset Value Nb6 (MSB) 51MF Offset Value Nb6 (MSB) 51MF Offset Value Nb7 (LSB) Octet25 51MF Offset Value Nb6 (MSB) 51MF Offset Value Nb7 (LSB) Octet27 Offset Value Nb4 (MSB) Nb4 (MSB)	E414=	51MF Offs			- NIL O (1.10		set Value N		
51MF Offset Value Nb6 (MSB) 51MF Offset Value Nb7 (LSB) Octet26 51MF Offset Value Nb5 (MSB LSB) Offset Value Nb4 (MSB) Nb4 (MSB)	Offset Value Nb8 (MSB)			Offiset Valu	·			Offset Value Nb10	
51MF	51MF Off		` '	LC (MCD)	51MF Of		` '	ILZ (LOD)	
	Offset Value Nb4	этин Оп		` ′	e Nb5 (MSE		iset value N	51MF Offset Value Nb6	
	_ `	fset Value N	b3 (MSB)		51MF Of	fset Value N	lb4 (LSB)	(LOB)	Octet28

8	7	6	5	4	3	2	1	
	51MF Off	set Value N	b2 (MSB)		51MF Of	fset Value N	b3 (LSB)	Octet29
BCC Nb19 (MSB)		51MF	Offset Value	e Nb1 (MSE	LSB)		51MF Offset Value Nb2 (LSB)	Octet30
BCC	Nb17 (MSB	LSB)	BCC	Nb18 (MSB	LSB)	BCC Nb	19 (LSB)	Octet31
BCC Nb	14 (MSB)	BCC	Nb15 (MSB	LSB)	BCC	Nb16 (MSB	LSB)	Octet32
BCC Nb11 (MSB)	BCC	Nb12 (MSB	LSB)	BCC	Nb13 (MSB		BCC Nb14 (LSB)	Octet33
BCC	Nb9 (MSB	LSB)	BCC	Nb10 (MSB	LSB)	BCC Nb	11 (LSB)	Octet34
BCC Nb	6 (MSB)	BCC	Nb7 (MSB I	LSB)	BCC	Nb8 (MSB	LSB)	Octet35
BCC Nb3 (MSB)	BCC	Nb4 (MSB	LSB)	BCC	Nb5 (MSB	LSB)	BCC Nb6 (LSB)	Octet36
BCC	Nb1 (MSB	LSB)	BCC	Nb2 (MSB	LSB)	BCC Nb	3 (LSB)	Octet37
			RTD Value I	Nb18 (MSB)				Octet38
RTD \	/alue Nb15	(MSB)		R	D Nb18 (LS	SB)		Octet39
			RTD Val	ue Nb15				Octet40
		RTD Value	Nb14 (MSB)			RTD Val	ue Nb15 SB)	Octet41
RTD Value Nb10 (MSB)				/alue Nb14	(LSB)			Octet42
			RTD Val	ue Nb10				Octet43
	RTD Value	Nb6 (MSB)			RTD Value	Nb10 (LSB)		Octet44
			RTD Va	lue Nb6				Octet45
		RTD	Value Nb5 (I	MSB)			RTD Value Nb6 (LSB)	Octet46
	llue Nb4 SB)			RTD Value	Nb5 (LSB)			Octet47
(IVIX	36)		RTD Va	lue Nb4				Octet48
	RTD	Value ID4 (I	MSB)		RTD	Value Nb4 (LSB)	Octet49
			RTD Value	ID4 (LSB)				Octet50
			RTD value	ID3 (MSB)				Octet51
RTD	Value ID2 (f	MSB)		RTD	Value ID3 (LSB)		Octet52
			RTD Va	lue ID2				Octet53
	RTD Value ID1 (MSB) RTD Value ID2 (LSB)						Octet54	
Serv Cell Lat (MSB)			RTD	Value ID1 (LSB)	Ì	,	Octet55
			Serv C	ell Lat				Octet56
			Serv C					Octet57
Serv Cell Long (MSB)			Ser	v Cell Lat (L	SB)			Octet58
Serv Cell Long						Octet59		
			Serv Ce					Octet60
Rel North Nb18 (MSB)			Serv	Cell Long (LSB)			Octet61

Rel East Nb18 (MSB) Rel North Nb15 (MSB) Rel East Nb15 (MSB)				lorth Nb18 (I	_SB)			Octet62
(MSB) Rel North Nb15 (MSB) Rel East Nb15			Rel E	ast Nb18 (I				
Rel North Nb15 (MSB) Rel East Nb15			Rel E	ast Nb18 (I				1
Nb15 (MSB) Rel East Nb15					.SB)			Octet63
(MSB) Rel East Nb15								
Nb15								
			Rel N	lorth Nb15 (I	_SB)			Octet64
Rel			Rel E	ast Nb15 (L	.SB)			Octet65
North Nb14								
(MSB)								
Rel East Nb14			Rel N	lorth Nb14 (I	_SB)			Octet66
(MSB)								
Rel			Rel E	ast Nb14 (L	.SB)			Octet67
North Nb10								
(MSB)								
Rel East Nb10			Rel N	lorth Nb10 (I	_SB)			Octet68
(MSB)								
Rel			Rel E	East Nb10 (L	.SB)			Octet69
North Nb6								
(MSB)								
Rel East Nb6			Rel N	North Nb6 (L	.SB)			Octet70
(MSB)								
Rel North			Rel	East Nb6 (L	SB)			Octet71
Nb5								
(MSB)			Dall	Landa NILE (I	CD)			0-4-470
Rel East Nb5			Reir	North Nb5 (L	.SB)			Octet72
(MSB)								
Rel North			Rel	East Nb5 (L	SB)			Octet73
Nb4								
(MSB) Rel East			Pal N	North Nh4 (I	SR)			Octet74
Nb4	Rel North Nb4 (LSB)						Octet/4	
(MSB)	Del Feet NL4 /I CD						Ootot75	
Rel North	Rel East Nb4 (LSB)						Octet75	
ID4								
(MSB) Rel East	Rel North ID4 (LSB)					Octet76		
ID4			1.011		,			2 3.3.7 0
(MSB) Rel North ID:	3 (MSR)			Rel Fact I	D4 (LSB)			Octet77
	ID3 (MSB) Rel East ID4 (LSB) East ID3 (MSB) Rel North ID3 (LSB)					Octet78		
	· ·	•		Kell				
ŀ	Rel North II		10D)		Rel East I		OD)	Octet79
	Rel E	East ID2 (M			Rel	North ID2 (L	•	Octet80
			ID1 (MSB)			Rel East	D2 (LSB)	Octet81
		Rel E	ast ID1 (MSB	LSB)			Rel North ID1 (LSB)	Octet82

Annex C (informative): Example of GPS Assistance Data Broadcast Message

This section gives an example of how the information IE should be packed into the GPS Assistance Data message. The example shown in Table C.1 below includes corrections for 12 satellites.

Table C.1: Example of a GPS Assistance Data (DGPS Correction) message with 11 satellites

1
Ciphering Serial Number (MSB, bits 15-10)
Ciphering Serial Number (bits 9-2) Or Spare
Ciphering Serial Number (bits 9-2) Or Spare Sp
Spare Spar
Spare Spar
Spare Clock Drift Present Number (bits 1-0) or Spare
Spare Drift Present Or Spare
4
9 Reference Location
9 Reference Location
10
10
or Spare 11 FN (bits 9-2)
Spare FN (bits 9-2) Or Spare
TN (bits 9-2) Or Spare
Spare Spare Spare Spare Spare Spare
12 BN (MSB bits 7 - 5) TN (bits 3-0) FN (LSB bits 1-or or spare) 13 GPS TOW (MSB bits 19-17) or Spare BN (LSB bits 4 - 0) or or spare) 14 GPS TOW (bits 16-9)
Spare Spare Spare 13 GPS TOW (MSB bits 19-17) or or Spare BN (LSB bits 4 - 0) or or Spare 14 GPS TOW (bits 16-9)
13 GPS TOW (MSB bits 19-17) BN (LSB bits 4 - 0) or or Spare Spare 14 GPS TOW (bits 16-9)
or or Spare Spare 14 GPS TOW (bits 16-9)
14 GPS TOW (bits 16-9)
15 GPS TOW (bits 8-1)
16 N_SAT (bits 3-0) Correction Status/Health GPS
(bits 2-0) TOW (LSB bi
17 Satellite ID (Sat 1) UDRE (Sat 1)
18 IODE (Sat 1)
19 PRC (Sat 1 – MSBs, 7 – 0)
20 PRC (Sat 1 – MSBs, 7 – 4) RRC (Sat 1 – LSBs, 3-0)
21 RRC (Sat 1 - LSBs, 7 - 4) Delta PRC (Sat 1 - LSBs, 3-0) 22 Delta PRC (Sat 1 - MSBs, 7 - 4) Delta RRC (Sat 1)
77 Satellite ID (Sat 12) UDRE (Sat 12
78 IODE (Sat 12)
79 PRC (Sat 12 – MSBs, 7 – 0)
80 PRC (Sat 12 – MSBs, 7 – 4) RRC (Sat 12 – LSBs, 3-0) 81 RRC (Sat 12 – LSBs , 7 – 4) Delta PRC (Sat 12 - LSBs, 3-0)
82 Delta PRC (Sat 12 – MSBs, 7 – 4) Delta PRC (Sat 12 – MSBs, 7 – 4) Delta RRC (Sat 12)

Annex D (informative): Change history

			Change history	
Meeting#	CR	Rev	Subject/Comment	New Version
SMG#30bis	-		Approved at SMG#30bis as Release 98	7.0.1
SMG#31			Version for Release 1999	8.0.0
SMG31bis	A003		Addition of Integrity Monitor and Enhancements to DGPS	8.1.0
SMG31bis	A005		Broadcast Message Enhancement for Assisted GPS	8.1.0
GP-01	A007		Ciphering of GPS Assistance Data Broadcast Message	8.2.0
-	-	-	References to GSM changed to references to 3GPP	8.2.0
			Format changed to 3GPP style	
GP-03	A009	1	Editorial correction to RTD Drift Factor IE presence information	8.3.0
GP-04	A010	1	References for LCS in Release 4 for GSM 04.35	44.035v4.0.0

History

	Document history				
V4.0.0	April 2001	Publication			